

# PDB Driver for the MC9S08GW64

by: **Tanya Malik**  
**Reference Design and Applications Group**  
**Noida**  
**India**

## 1 Introduction

This document describes a driver for a Programmable Delay Block (PDB), allowing users to customize all the possible configurations for this peripheral.

The software architecture is designed to provide seamless migration between devices that have the same peripheral module.

In this application note, the driver interfaces are explained. Various applications for the MC9S08GW64 can make use of this driver. The following sections describe details and steps for creating an application using the PDB driver.

The primary function of the programmable delay block is simply to provide controllable delays from either an external trigger, or a programmable interval tick, to the sample trigger input of one or more ADCs.

### 1.1 Programmable Delay Block (PDB) in MC9S08GW64

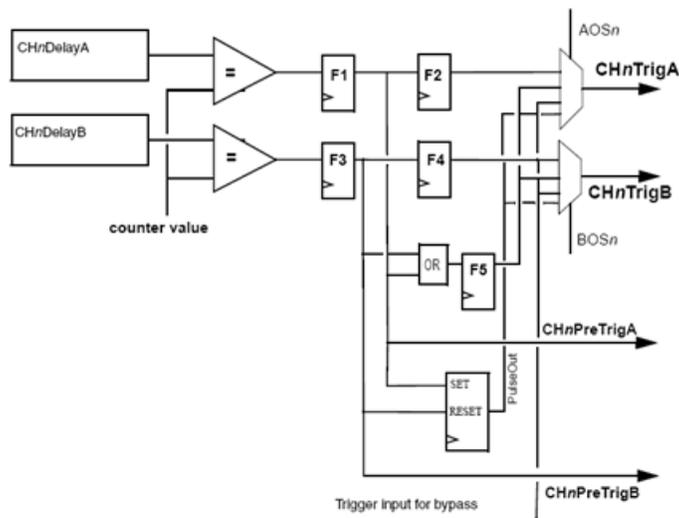
The MC9S08GW64 series includes a PDB block used to provide a trigger to the two ADC trigger select inputs. The clock to the PDB module can be gated on or off by using the SCGC4\_PDB bit of the System clock gating control 4 register. On reset the clock is gated to the PDB module.

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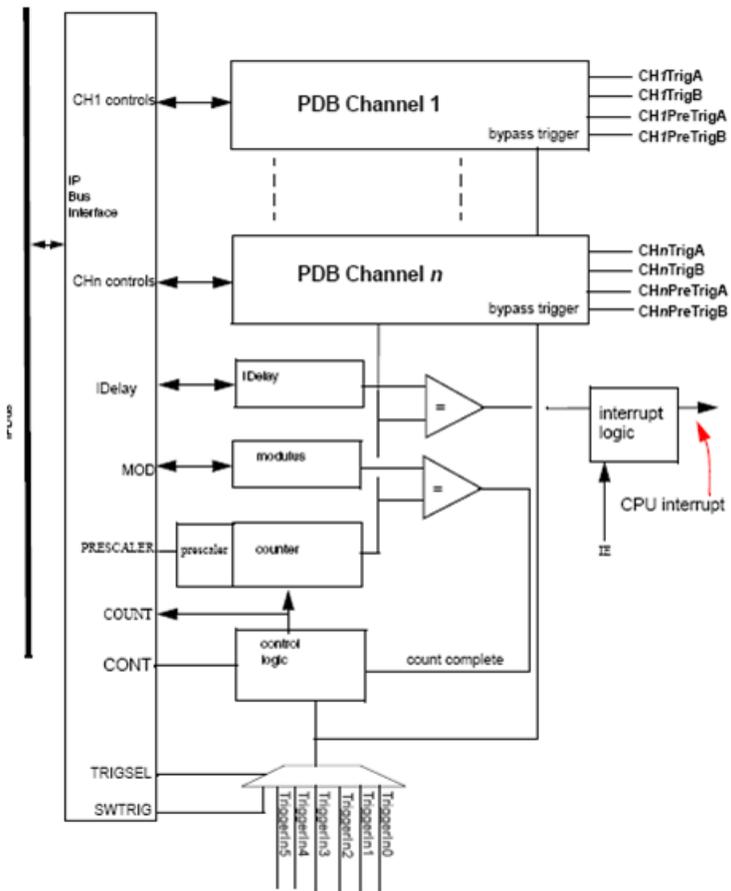
## 1.2 Block Diagram

The following block diagram shows that the PDB block generates four triggers — pre-trigger for channel A, trigger for channel A, pre-trigger for channel B, and trigger for channel B.



**Figure 1. PDB channel block diagram**

DelayA and DelayB determine the time between assertion of the trigger input to the point at where changes in the trigger output signals are initiated.



**Figure 2. n Channel PDB block diagram**

Pre-triggerA and Pre-triggerB are used to precondition the ADC blocks two bus clock periods prior to the actual measurement trigger. The Pre-Trigger signals are used to specify what signal will be sampled next. When PreTriggerA and TriggerA are asserted, the ADC conversion is triggered with set A of the control and results registers. When PreTriggerB and TriggerB are asserted, the ADC conversion is triggered with set B of the control and results register.



**Figure 3. Decoupled A and B trigger generation**

The PDB Channeln, PreTriggerA, and PreTriggerB are connected to ADCn Trigger Select Events ADHWTSa and ADHWTSB correspondingly. Either TriggerA or TriggerB can trigger the ADC conversion. When TriggerA triggers the ADC conversion, control and results register set A is used. When TriggerB triggers the ADC conversion, control and results register set B is used.

## 1.3 Error Conditions

The Delay A and Delay B registers must be configured to make the next trigger asserted after the previous ADC conversion is finished. When one conversion triggered by TriggerA is in progress, the TriggerB output is suppressed until the ADCnSC1A\_COCO bit is set. If Delay B is timed-out during the ADC conversion triggered by TriggerA, the Sequence Error bit PDBCHnSC\_ERRB will be set, see Figure 4.

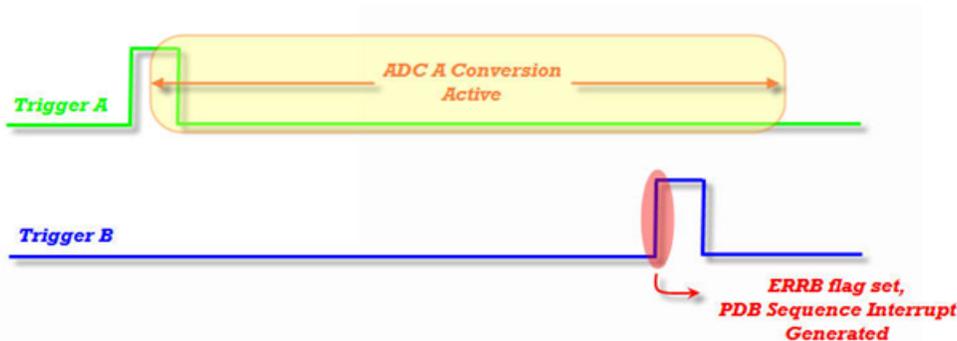


Figure 4. PDB error B

When one conversion, triggered by TriggerB is in progress, the TriggerA output is suppressed until the ADCnSC1B\_COCO bit is set. If Delay A is timed out during the ADC conversion triggered by TriggerB, the Sequence Error bit PDBCHnSC\_ERRA will be set.

Figure 5 shows the normal conversion without errors.

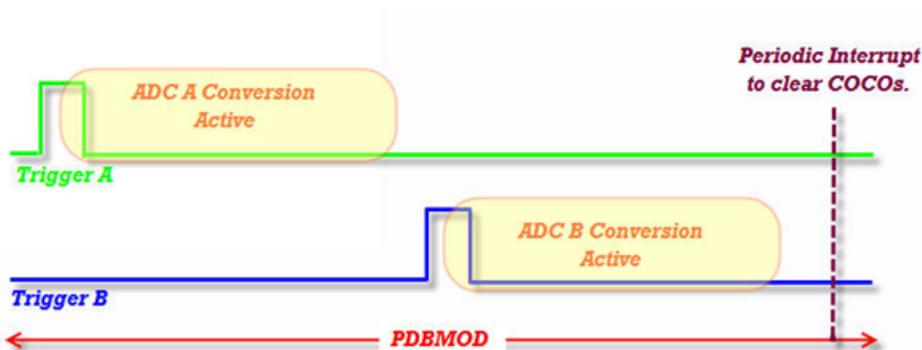


Figure 5. Conversion without PDB error

## 2 Software Driver Description

The PDB driver is provided as C code files. You can add these files to your applications. With the integration of the PDB driver, PDB driver APIs can be called to use the PDB functionality in your application.

There are three files associated with the PDB driver. The following is a brief description:

pdb.h—It contains all the high level API declarations and the various macros to be used in the functions. It defines the structure of the various PDB registers.

pdb.c—It is the main file for the driver. It contains the various high level API definitions.

## 2.1 pdb.h

### NOTE

The macros provided are passed as arguments to the respective functions to get the required configuration. They are explained in detail in Section 2.2 [pdb.c](#)

**Table 1. Macros**

Macros	Descriptions
#define PDB_PRESCALER_1	There are macros used to select the pre-scaler for the pdb clock.
#define PDB_PRESCALER_2	
#define PDB_PRESCALER_4	
#define PDB_PRESCALER_8	
#define PDB_PRESCALER_16	
#define PDB_PRESCALER_32	
#define PDB_PRESCALER_64	
#define PDB_PRESCALER_128	
#define PDB_CONT_MODE	Used to select between running the PDB in continuously or in one shot. In continuous mode, the PDB is configured to provide trigger continuously after the fixed duration.
#define PDB_ONE_SHOT_MODE	
#define PDB_COMP1_TRIG_SEL	Can be used to select the input trigger for the PDB module. The input trigger for the PDB block can be the comparator output, external trigger, or software trigger.
#define PDB_COMP2_TRIG_SEL	
#define PDB_EX_TRIG_SEL	
#define PDB_SW_TRIG_SEL	
#define PDB_IDELAY_INT_ENABLE	Used to enable or disable the idelay interrupt for the PDB module. This feature can be used to schedule an independent interrupt at some point in the PDB cycle.
#define PDB_IDELAY_INT_DISABLE	
#define PDB_CHANNEL_1_TRIG_A	Used to specify the type of error occurred. If a conversion is triggered by macros.
#define PDB_CHANNEL_1_TRIG_B	
#define PDB_CHANNEL_2_TRIG_A	
#define PDB_CHANNEL_2_TRIG_B	
#define PDB_IDELAY_INTERRUPT	

## 2.2 pdb.c

It contains the definition of various functions to configure and use the various features of the PDB.

### 2.2.1 PDB\_Init

Description:

This function initializes the specific PDB interface by configuring the internal registers. The function is used to set the PDB clock prescaler, enable and disable the interrupt, select the mode, and the type of trigger required to the PDB.

## Software Driver Description

Prototype:

```
void PDB_Init(unsigned char Prescaler, unsigned char Continuous_OneShot_Mode, unsigned char Trig_Select, unsigned char Idelay_Interrupt_Enable, void (*p)(unsigned char))
```

Input parameters:

- Prescaler—To select the prescaler of the PDB clock using the macros  
PDB\_PRESCALER\_1, PDB\_PRESCALER\_2, PDB\_PRESCALER\_4,  
PDB\_PRESCALER\_8, PDB\_PRESCALER\_16  
PDB\_PRESCALER\_32, PDB\_PRESCALER\_64,  
PDB\_PRESCALER\_128
- Continuous\_OneShot\_Mode—To select between the continuous trigger mode or one shot mode using the macros.  
PDB\_CONT\_MODE, PDB\_ONE\_SHOT\_MODE
- Trig\_Select—To select the trigger select for the PDB module between the external, internal, comparator 1 output, and comparator 2 output by using the following macros:  
PDB\_COMP1\_TRIG\_SEL, PDB\_COMP2\_TRIG\_SEL  
PDB\_EX\_TRIG\_SEL, PDB\_SW\_TRIG\_SEL
- Idelay\_Interrupt\_Enable—To enable or disable the idelay interrupt by using the macros:  
PDB\_IDELAY\_INT\_ENABLE, PDB\_IDELAY\_INT\_DISABLE
- p—Callback function address passed as input. The user can either pass the address of the function to be called in case of an interrupt or it can pass 0 if no callback function is required.
- char—Argument to the callback function. It specifies which type of PDB interrupt has occurred.

Output parameters:

None

Example:

```
void callback(void)
{
}
PDB_Init(PDB_PRESCALER_2, PDB_CONT_MODE,
        PDB_SW_TRIG_SEL, PDB_IDELAY_INT_ENABLE,
        &callback)
```

Initializes PDB with peripheral clock/2 as the PDB clock, continuous trigger mode, software trigger select, idelay interrupt enabled, and the address of the callback function passed.

### NOTE

The Callback function is created by the user according to the user's requirements.

## 2.2.2 PDB\_Set\_Mod\_Idelay

Description:

This function is used to select the mod value of the PDB counter and the idelay value, after which the interrupt to the MCU is required.

Prototype:

```
void PDB_Set_Mod_Idelay(unsigned int Mod_Value, unsigned int Idelay)
```

Input parameters:

- Mod\_Value—Enter the mod value of the counter
- Idelay—Enter the idelay value, then the interrupt is required for the MCU

Output parameters:

None

Example:

```
PDB_Set_Mod_Idelay(0xFFFF,0xFFFF)
Configures the PDB with mod and idelay values.
```

### 2.2.3 PDB\_Set\_Ch1\_Delay\_A

Description:

This function sets the channel1 delay then pretrigger A is required and enables the interrupt for pdb error A on channel 1.

Prototype:

```
void PDB_Set_Ch1_Delay_A(unsigned int ChannelA_Delay)
```

Input parameters:

- ChannelA\_Delay—Enter the delay required for pretrigger A in pdb channel1

Output parameters:

None

Example:

```
PDB_Set_Ch1_Delay_A(0x000F)
```

### 2.2.4 PDB\_Set\_Ch1\_Delay\_B

Description:

This function sets the delay of channel1 then pretrigger B is required and enables the pdb error B on channel 1.

Prototype:

```
void PDB_Set_Ch1_Delay_B(unsigned int ChannelB_Delay)
```

Input parameters:

- ChannelB\_Delay—Enter the delay required for pretrigger B in pdb channel1

Output parameters:

None

Example:

```
PDB_Set_Ch1_Delay_B(0x00FF)
```

### 2.2.5 PDB\_Set\_Ch2\_Delay\_A

Description:

This function sets the channel2 delay then pretrigger A is required and enables the pdb error A on channel 2.

Prototype:

```
void PDB_Set_Ch2_Delay_A(unsigned int ChannelA_Delay)
```

Input parameters:

- ChannelA\_Delay—Enter the delay required for pretrigger A in pdb channel2

## Software Driver Description

Output parameters:

None

Example:

```
PDB_Set_Ch2_Delay_A(0x000F)
```

### 2.2.6 PDB\_Set\_Ch2\_Delay\_B

Description:

This function sets the channel1 delay then pretrigger B is required and enables the pdb error B on channel 2.

Prototype:

```
void PDB_Set_Ch2_Delay_B(unsigned int ChannelB_Delay)
```

Input parameters:

ChannelB\_Delay—Enter the delay required for pretrigger B in pdb channel 2

Output parameters:

None

Example:

```
PDB_Set_Ch2_Delay_B(0x00FF)
```

### 2.2.7 PDB\_Start\_SW\_Trigger

Description:

This function starts the conversion by giving software trigger.

#### NOTE

Only if trigger select is PDB\_SW\_TRIG\_SEL

Prototype:

```
void PDB_Start_SW_Trigger(void)
```

Input parameters:

None

Output parameters:

None

Example:

```
PDB_Start_SW_Trigger()
```

### 2.2.8 Interrupt Subroutines

There are two types of interrupts:

- Idelay interrupt—It occurs when the value of PDB counter matches the idelay value
- PDB error interrupt—There are two types of errors as described in Error Conditions

There are two interrupt subroutines as follows:

#### **pdb\_isr**

Description:

This subroutine is called when the pdb counter value matches the idelay value.

Prototype:

```
void interrupt VectorNumber_Vpdb pdb_isr(void)
```

Input parameters:  
None

Output parameters:  
None

### **pdb\_isr\_err**

Description:  
This subroutine is called either errA or errB and occurs on either PDB channel1 or channel2.

Prototype:  
void interrupt VectorNumber\_Vpdb pdb\_isr(void)

Input parameters:  
None

Output parameters:  
None

### **NOTE**

If the address of the callback function is passed in the PDB\_Init function, the interrupt subroutine then jumps to the callback function and the user can write the action taken in the callback function.

## **3 Assumptions**

The descriptions in this document assumes the person reading it has full knowledge of all the configuration registers of all the blocks in 9S08GW64, especially LCD and ICS(Internal Clock Source) blocks.

## **4 Use Case**

Assuming that the clock settings are done and the bus clock is running on 20 Mhz. Include pdb.h in the main file.

Step 1—Initialize the PDB with the required configuration:  

```
PDB_Init(PDB_PRESCALER_2,PDB_ONE_SHOT_MODE
PDB_SW_TRIG_SEL,PDB_IDELAY_INT_DISABLE,&callback);
```

It initializes the PDB module with prescaler 2, one shot mode, software trigger select, idelay interrupt disabled, and the address of the callback function is passed.

Step 2—Sets the mod value and idelay value  

```
PDB_Set_Mod_Idelay(0xFFFF,0xFFFF);
```

Step 3—Sets the delay after which pretrigger A and pretrigger B is required on channel 2.  

```
PDB_Set_Ch2_Delay_A(0x000F);
PDB_Set_Ch2_Delay_B(0xFFFF);
```

Step 4—Starts the PDB module by providing the software trigger  

```
PDB_Start_SW_Trigger();
```

## 5 Conclusion

This driver provides a software base for applications that need the implementation of the PDB.

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