Application Note

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Cycle-by-Cycle Instruction Set Details for the M68HC08 Family of MCUs

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Introduction

This application note provides detailed information, not previously published, about the cycle-by-cycle behavior of CPU M68HC08 instructions. Although most applications do not require this level of detail, it can be very useful in unusual cases where it is important to carefully control the timing of control sequences or the relative timing of I/O events. This level of detail also helps users understand exactly how read-modify-write instructions work.

NOTE: *With the exception of mask set errata documents, if any other Motorola document contains information that conflicts with the information in the device data sheet, the device data sheet should be considered to have the most current and correct data.*

Cycle Codes

This document uses the shorthand notation that is used to document cycle-by-cycle details in the HCS08 and HCS12 instruction sets. This shorthand uses one character to mnemonically represent each bus cycle. For example, a lowercase `p` is used to represent a program fetch cycle. In the HC08 CPU, all bus cycles refer to 8-bit data so all of the mnemonic cycle codes use lowercase letters. In the HCS12, some bus cycles used uppercase letters to indicate 16-bit memory accesses. The cycle-by-cycle codes used for the HC08 CPU are explained in the following paragraphs.

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Program Fetch Cycle – p – Used to fetch the next byte of object code from program memory. When any HC08 instruction starts, the first byte of object code for that instruction is already in the CPU's instruction buffer. Each instruction includes enough p cycles to replace the number of bytes of object code for that instruction.

Figure 1 shows the timing diagram for internal clock and bus signals during a program fetch cycle.

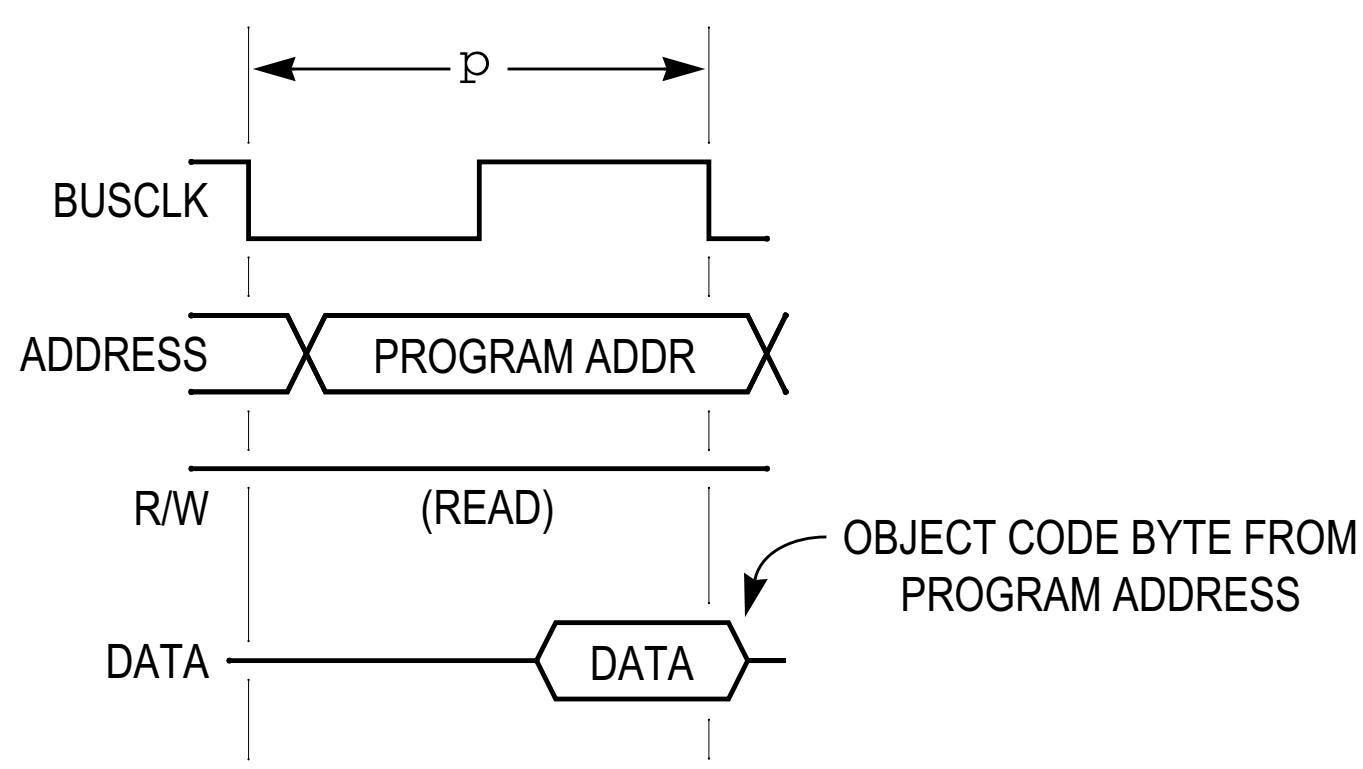

Figure 1. Timing Waveforms for a Program Fetch (p) Cycle

For example, when a 2-byte instruction such as ADD (direct addressing mode) is executed, the opcode ($BB) is already in the CPU's instruction buffer. The instruction then performs one p cycle to fetch the low half of the direct address of the operand, uses this address to read the operand from memory, and then performs a second p cycle to fetch the opcode of the next instruction.

Byte Read Cycle – `r` – Used to read one byte of operand data from memory.

Figure 2 shows the timing diagram for internal clock and bus signals during a data read cycle. If the operand address corresponds to an input port pin, there will usually be a simple synchronizer circuit associated with the signal so that the value on the data bus does not change state for a setup-and-hold time near the falling edge of the bus clock. Because the internal BUSCLK signal is not visible outside the MCU, you should think of the read as taking place sometime during the last half of the BUSCLK cycle.

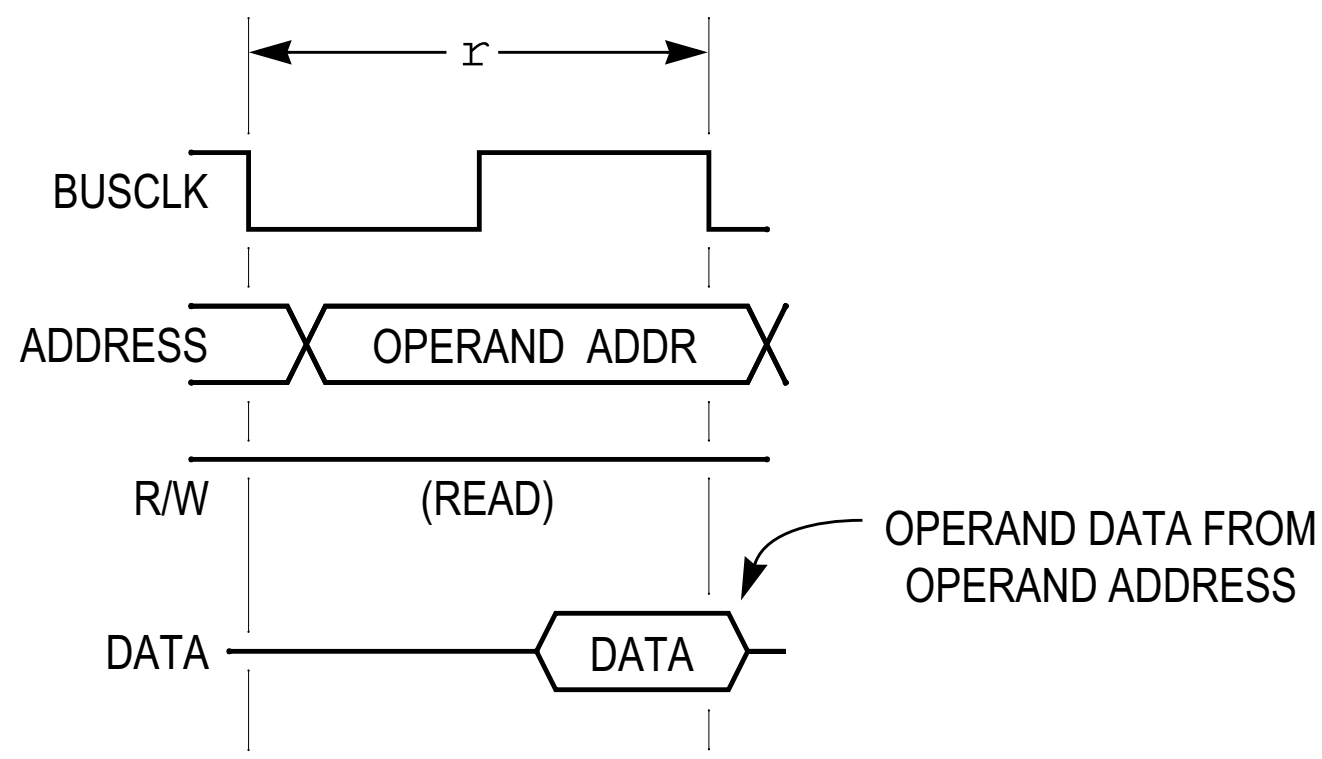

Figure 2. Timing Waveforms for a Data Read (`r`) Cycle

Byte Write Cycle – w – Used to write one byte of operand data to memory.

Figure 3 shows the timing diagram for internal clock and bus signals during a data write cycle. The write takes place during the last half of the bus cycle. In the case where the operand address corresponds to an output port pin, the pin changes state one propagation delay after the middle of the bus cycle.

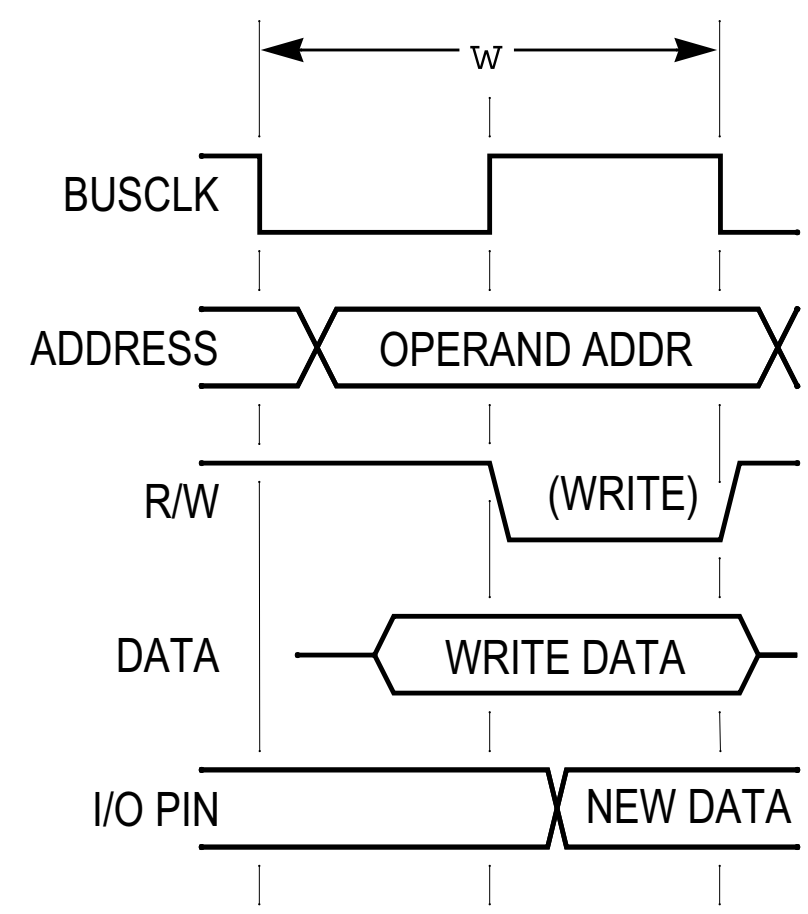

Figure 3. Timing Waveforms for a Write (w) Cycle

Stack Write (Push) Cycle – `s` – Used to write (push) one byte of data to the next available location on the system stack. The stack in the M68HC08 builds from higher addresses to lower addresses, and the stack pointer (SP) always points to the next available location on the stack.

Figure 4 shows the timing diagram for internal clock and bus signals during a stack write cycle.

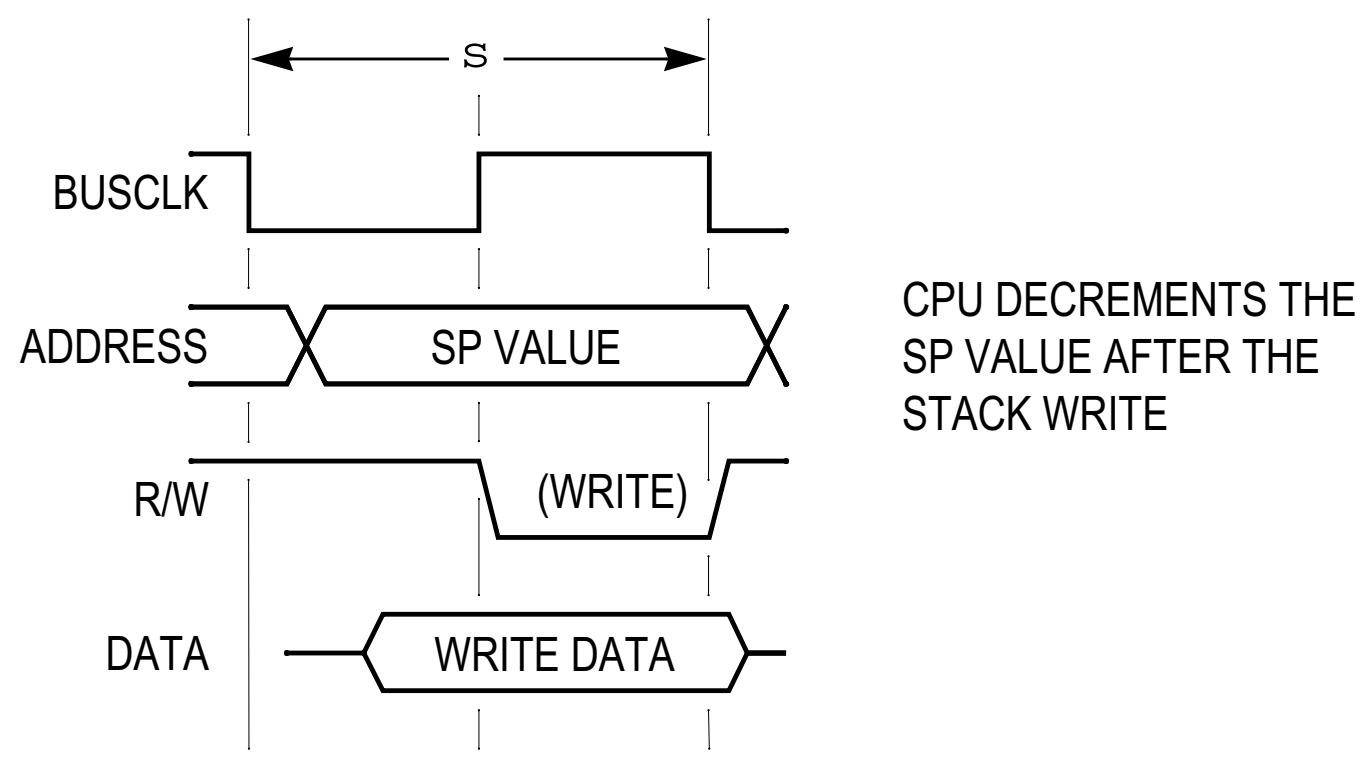

Figure 4. Timing Waveforms for a Stack Write (`s`) Cycle

For example, a PSHA instruction is a 2-cycle instruction with the shorthand code `ps` where the `p` cycle fetches a byte of object code to make up for the one byte of object code needed for the PSHA instruction. The `s` cycle is used to store the contents of the accumulator at the location pointed-to by SP. Then SP is decremented to point at the next available location on the stack.

Stack Read (Pop) Cycle – `u` – Used to unstack or read (pop) one byte of data from the system stack. For example a PULA instruction is a 2-cycle instruction with the shorthand code `pu`. The `p` cycle fetches a byte of object code to make up for the one byte of object code needed for the PULA instruction. The `u` cycle is used to get one byte of data from the stack by incrementing SP by one and then reading the value pointed-to by SP into the accumulator.

Figure 5 shows the timing diagram for internal clock and bus signals during a stack read cycle.

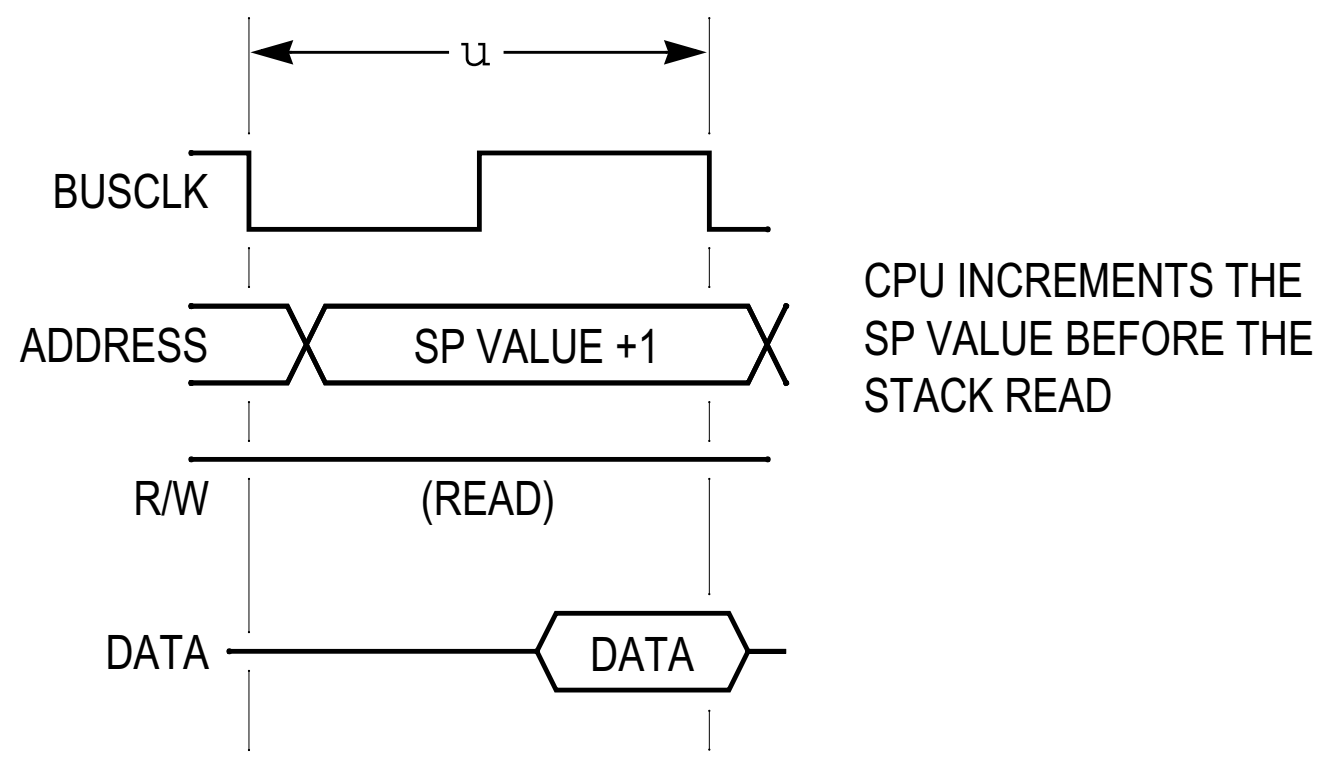

Figure 5. Timing Waveforms for a Stack Read (`u`) Cycle

Vector Fetch Cycle – v – Used to fetch one-half of a 16-bit interrupt or reset vector from memory. v cycles are always found in pairs to fetch the high and low bytes of a 16-bit vector, respectively.

Figure 6 shows the timing diagram for internal clock and bus signals during a pair of vector fetch cycles. During these two v cycles, the data that is read from the vector addresses is loaded directly into the program counter high and low halves (PCH and PCL), respectively. The next cycle after a pair of vector fetch cycles is always a program fetch cycle (not shown in this figure) using the address that was loaded into PCH and PCL by the two v cycles.

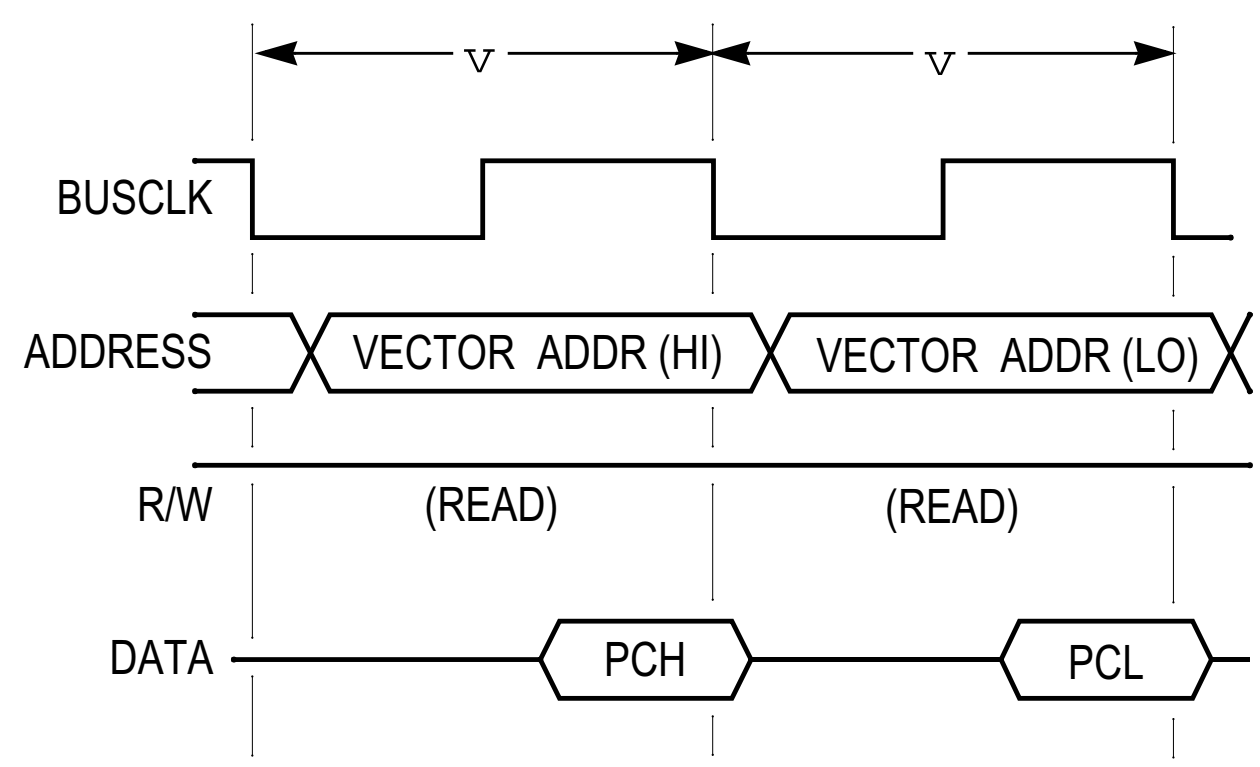

Figure 6. Timing Waveforms for Two Vector Fetch (v) Cycles

Dummy (Read) Cycles – `d` – Used to perform internal operations where no new information is read or written using system address and data buses. In these cases, a dummy read cycle is performed using the same address as the previous bus cycle. The data from a `d` cycle is ignored.

Figure 7 shows the timing diagram for internal clock and bus signals during a dummy cycle.

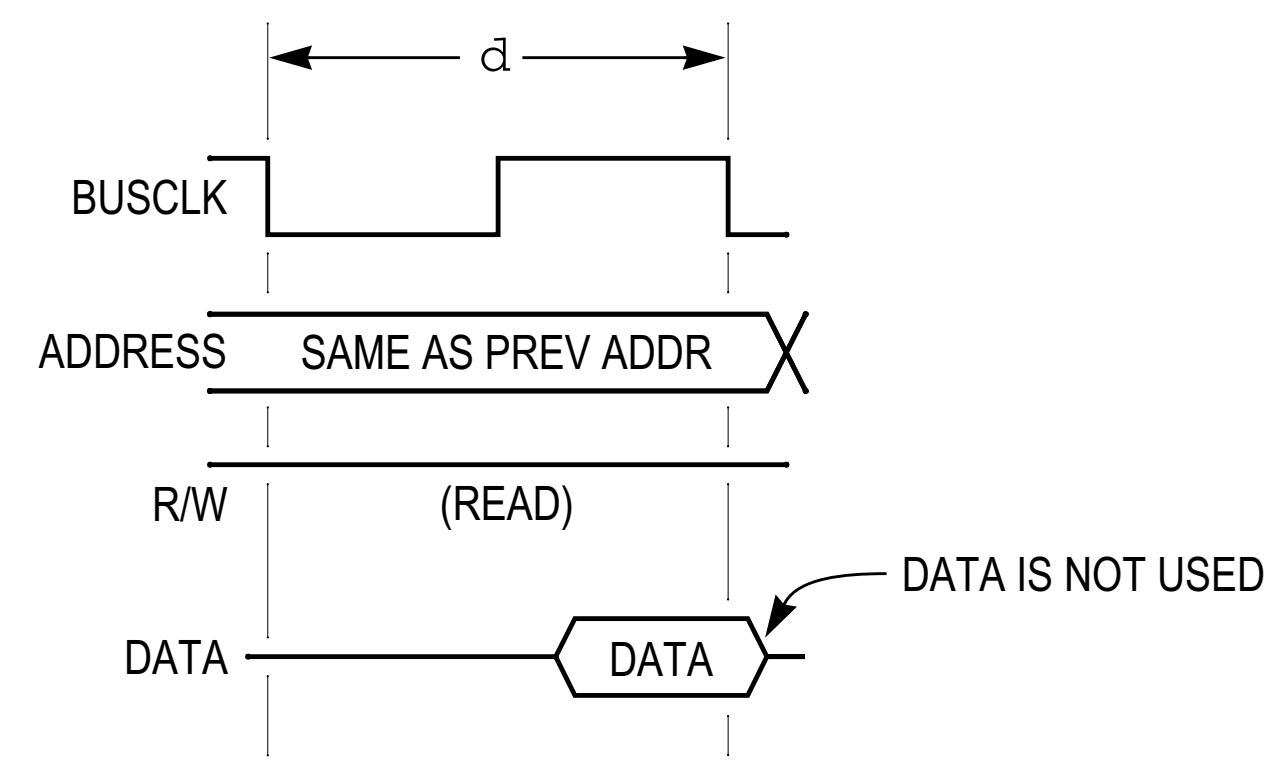

Figure 7. Timing Waveforms for a Dummy (`d`) Cycle

Interpreting Cycle-by-Cycle Code Sequences

This section will discuss an example timing diagram of internal bus and control signals during the execution of a BCLR instruction. After the meaning of the code letters is understood, you will not need to see cycle-by-cycle details as timing diagrams. The cycle-by-cycle code sequence for a BCLR 0,*opr8a* instruction is `prwp`. Because there are four code letters, the instruction takes four bus cycles. **Figure 8** shows this 4-cycle sequence for a BCLR instruction that will generate a falling edge on the port B, bit 0, pin.

```
"    "  "       "         "     "          "
8310 11 01      loop:     BCLR  Bit_0,PortB  ;[4] drive PTB0 low
8312 20 FC                BRA   loop         ;[3] repeat
"    "  "       "         "     "          "
```

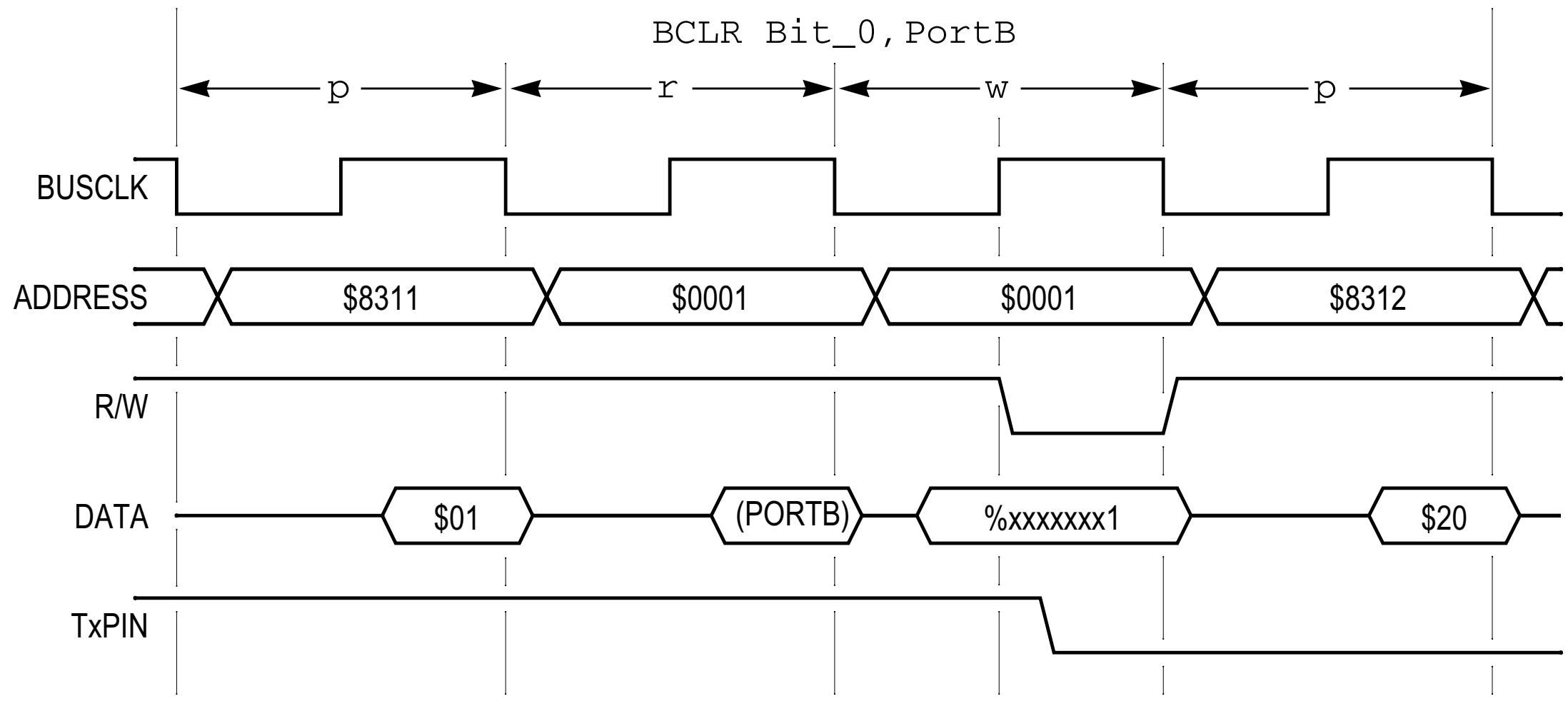

Figure 8. Timing Details for a BCLR Instruction

The top portion of this figure shows two program listing lines, including the BCLR instruction. Because the first byte of object code for the next instruction ($20) will be fetched during the BCLR instruction, the BRA instruction line is also shown. The 4-digit hexadecimal number at the beginning of each of these lines is the program address for the first byte of object code for the instruction. In the case of the BCLR 0,*oper8a* instruction, the opcode is $11 and the $01 is the low half of the address for the operand.

Remember that when an instruction starts to execute, the first byte of object code for the instruction is already in the CPU's instruction buffer because it was fetched during the previous instruction. So, the first `p` cycle fetches the second byte of object code ($01) for the BCLR instruction from address $8311. Between the first and second cycles of this instruction, the CPU constructs the address of the operand by using this $01 as the low half of an address in the range $0000–$00FF. The second cycle of this BCLR instruction (`r`) reads the current contents of the port B register from this constructed address ($0001). Between the second and third cycles, the CPU forces bit 0 of the value that was read from port B to a 1. During the third cycle (`w`), the CPU writes this modified data value back to port B at $0001. During the fourth cycle (`p`), the CPU reads the next byte of object code ($20) from address $8312. This is the BRA opcode and it is loaded into the instruction buffer so that the CPU will be ready to execute the first cycle of the next instruction immediately following the fourth cycle of the BCLR instruction.

Hardware Reset

Resets cause registers and systems inside the MCU to assume default values. The reset sequence includes several sequential events and tests before the CPU begins executing instructions. After the hardware reset sequence is completed, the CPU performs two `v` cycles to fetch the high byte of the reset vector from $FFFE and the low byte from $FFFF, respectively. It then performs one `p` cycle to pre-load the CPU's instruction buffer with the opcode of the first instruction. Execution then continues using the cycle-by-cycle sequences for each consecutive instruction. There are no gaps between the cycle-by-cycle sequences for reset, instructions, or interrupts. So if the first instruction of an application program was an LDA (immediate) instruction, the CPU would execute the sequence `vvp` for the reset, immediately followed by `pp` for the LDA (immediate) instruction.

Interrupts

Hardware interrupts are an exception to the sequential flow of program instructions. When an interrupt occurs, the CPU completes the instruction that is currently being executed and then responds to the interrupt. The interrupt sequence uses the same 9-cycle sequence as an SWI instruction (`psssssvvp`). The first `p` cycle is a fetch of the program byte that would have been fetched if the interrupt had not occurred. This data will not be used by the CPU, but the fetch was already scheduled before the interrupt occurred. The next five `s` cycles of the interrupt sequence store (push) the return address low, return address high, X, A, and CCR onto the stack so the CPU can resume the interrupted program at the point where it was interrupted (after completing the interrupt service routine (ISR)). The next two `v` cycles fetch the high and low halves of the interrupt vector for the highest priority source that caused the interrupt. Finally, a `p` cycle is executed to pre-fill the instruction buffer with the opcode of the first instruction of the ISR.

Usually, the ISR would end with a 7-cycle RTI instruction (`puuuuup`), which recovers the previously saved CPU state and resumes execution of the original program as if the interrupt had not occurred.

Conditional Branches

Conditional branch instructions execute one of two different sequences depending upon whether the branch condition was true. In the case of the BRN instruction, the branch condition is never true. Therefore, the sequence is `pdp` where the first `p` cycle fetches the second byte of object code for the branch instruction (the offset byte). The next `d` cycle is a dummy read from the same address. During the `d` cycle, the CPU adds the offset to the program counter. This gets the pointer to the instruction at the branch destination. Because the BRN instruction never branches, this calculated address is not used. Instead, the branch is not taken, and the third cycle (`p`) fetches the opcode of the next instruction after the BRN instruction.

When the branch condition for a branch instruction is true, the sequence is the same except the last `p` cycle fetches the opcode of the instruction at the branch destination rather than the opcode of the instruction immediately after the conditional branch instruction.

BRSET and BRCLR instructions have a 5-cycle sequence (`prpdp`). The first `p` cycle fetches the low half of the operand's direct address. The `r` cycle fetches the whole 8-bit operand from the direct memory location that contains the bit that will be tested. The second `p` cycle is used to fetch the branch offset while the specified bit is tested in the operand that was just fetched. The next `d` cycle is a dummy read from the same address while the CPU is adding the offset to the program counter to get the pointer to the instruction at the branch destination. The last `p` cycle fetches the opcode of the next instruction from either the destination address or the next address after the offset, depending on whether the branch condition was true or false, respectively.

Similarly, the last `p` cycle of a CBEQ or DBNZ instruction fetches the opcode of the next instruction from either the destination address or the next address after the offset, depending on whether the branch condition was true or false, respectively.

Cycle-Timed Code

Although you don't need to know the cycle-by-cycle details of instructions for most application programs, there are times when this information is critical. For example, suppose you want to write a program that transmits or receives serial data using software and general-purpose I/O pins to create an RS232 serial communications interface (SCI). In such a case, it may be possible to write a program that can send or receive at a slightly faster baud rate if you know the timing of reads and writes at the cycle level instead of the instruction level. For example, in direct and extended addressing mode variations of STA

instructions, the write takes place in the next-to-last cycle of the instruction, but in the indexed addressing mode variations, the write occurs in the last cycle of the instruction. The position of the read cycle in LDA instructions is similar.

To demonstrate how you would use the detailed cycle-by-cycle information, we will study an example routine. The program segment in **Listing 1** is the working portion of a software SCI transmit routine. A general-purpose I/O pin at bit number TxBit, in the I/O port corresponding to the data direction register TxDDR, will be used as our TxD pin. The port bit corresponding to this pin was previously written to 0 and the associated pullup was enabled (or an external pullup resistor is connected). When the DDR bit is 0, the pin behaves as a high-impedance input that is pulled high. When the DDR bit is set to 1, the pin behaves as an output pin that is driven low. The 8-bit data value was previously pushed onto the stack, and because another value was also previously pushed, the data will be at `3,SP` after the PSHX at `putbyte3:`

```
 "           "      "               "
putbyte3: pshx                   ;store delay counter
          lda    #10             ;start, 8 data, stop = 10 loops
          sec                    ;becomes stop bit after 9 RORs
          bra    outLow          ;[3] Tx a low for start bit

PutLoop:  ror    3,SP            ;[5] LSB to C-bit, Tx that level
          bcc    outLow          ;[3] if C=0 Tx low, else Tx a hi
outHi:    bclr   TxBit,TxDDR     ;[4] PTA0 input pulls up to high
          bra    outDelay        ;[3] go to time 1 bit delay
outLow:   bset   TxBit,TxDDR     ;[4] PTA0 output makes pin drive low
          bra    outDelay        ;[3] time 1 bit delay (match time)
outDelay: dbnzx  *               ;[3] loop 3~ * (value in X)
          pulx                   ;[2]
          pshx                   ;[2]
          dbnza  PutLoop         ;[3] repeat for start, 8 data, stop
  "           "      "               "
```

Listing 1. Partial Code Listing for SCI Transmit Routine

We will map out the cycle-by-cycle operation of this routine starting from the `bra outLow` instruction above `PutLoop:` until the program has generated the start bit and the first data bit of the transmit value. We will assume that the first data bit is a 1 so we can easily see the bit time boundaries. We also assume the I/O pin associated with TxBit was acting as an input and was pulled up before starting this routine.

Listing 2 shows the instructions in the order that they would be executed (starting from the `bra outLow` instruction just above the `PutLoop:` label in **Listing 1**). This listing shows instructions in execution order so some instructions and sequences are repeated (such as the DBNZX instruction that is used to form a bit-time delay). For this example, we will assume X is 2 at the start of the routine to simplify our drawings. In the actual SCI transmit routine, X would be set to make the delay for a bit time equal to the appropriate length for the desired baud rate and bus speed.

Listing 2 also shows the cycle-by-cycle details for each instruction. For example, the `outLow:   bset   TxBit,TxDDR` instruction is made up of the 4-cycle sequence `prwp`. The first `p` cycle fetches the direct address for the BSET instruction. The second cycle is a byte read of the operand (the current contents of the TxDDR register). Between the second and third cycles of the BSET instruction, the CPU sets the TxBit in this value. The third cycle is a write of the modified value back to the TxDDR register. And finally, the last cycle is a program fetch to refill the instruction buffer in preparation for the next instruction.

From **Listing 2**, we can see that the transmit data pin will go low during the third cycle of the `outLow:   bset   TxBit,TxDDR` instruction, and the start bit will end exactly 28 cycles later in the third cycle of the `outHi:   bclr   TxBit,TxDDR` instruction. We can also see that the transmit data pin will go low again at the end of the LSB data bit exactly 28 cycles later during the `outLow:   bset   TxBit,TxDDR` instruction at the bottom of **Listing 2**.

```
      ___________________________________
_ p _           bra    outLow
_ d _
_ p ___________________________________
_ p outLow:     bset   TxBit,TxDDR
_ r _
_ w _  -------------------------   <-beginning of start bit
_ p ___________________________________
_ p _           bra    outDelay
_ d _
_ p ___________________________________
_ p outDelay:   dbnzx  *
_ d _
_ p ___________________________________
_ p outDelay:   dbnzx  *
_ d _
_ p ___________________________________
_ p _           pulx
_ u ___________________________________
_ p _           pshx
_ s ___________________________________
_ p _           dbnza  PutLoop
_ d _
_ p ___________________________________
_ p PutLoop:    ror    3,SP
_ p _
_ p _
_ r _
_ w ___________________________________
_ p _           bcc    outLow
_ d _
_ p ___________________________________
_ p outHi:      bclr   TxBit,TxDDR
_ r _
_ w _  -------------------------   <-end of start bit
_ p ___________________________________
_ p _           bra    outDelay
_ d _
_ p ___________________________________
_ p outDelay:   dbnzx  *
_ d _
_ p ___________________________________
_ p outDelay:   dbnzx  *
_ d _
_ p ___________________________________
_ p _           pulx
_ u ___________________________________
_ p _           pshx
_ s ___________________________________
_ p _           dbnza  PutLoop
_ d _
_ p ___________________________________
_ p PutLoop:    ror    3,SP
_ p _
_ p _
_ r _
_ w ___________________________________
_ p _           bcc    outLow
_ d _
_ p ___________________________________
_ p outLow:     bset   TxBit,TxDDR
_ r _
_ w _  -------------------------   <- end of LSB (bit-0)
_ p ___________________________________
```

Listing 2. Instruction Order Listing (with Cycle Details)

Conclusion

This application note explains the cycle-by-cycle details for each addressing mode of each instruction that is included in the instruction set summary for the M68HC08 CPU. Cycle-by-cycle details for each addressing mode of each instruction are provided in a new column near the right side of the instruction set summary table. A shorthand (code) was used to provide this detailed information in a compact form where each bus cycle is represented by a single mnemonic character. The code letters were explained. Several special operations including reset, interrupts, and branches were also explained using the same bus cycle codes. Finally, a code example was used to explain how this cycle-by-cycle information can be used while writing software routines that can control I/O pins with one-cycle precision.

This application note can also help users understand how the M68HC08 CPU executes instructions. For example, the cycle-by-cycle detail for a BSET or BCLR instruction shows that these instructions are read-modify-write instructions. This means these instructions read the entire 8-bit location, internally modify the selected bit within that value, and then re-write the modified value to the memory location. Without this level of detail, it could appear that the CPU somehow wrote to a single bit without reading or writing other bits in the memory location.

Appendix A — Instruction Set Summary

Table 1 provides a summary of the M68HC08 instruction set in all possible addressing modes. The table shows operand construction, execution time in internal bus clock cycles, and cycle-by-cycle details for each addressing mode variation of each instruction.

Table 1. Instruction Set Summary (Sheet 1 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR V 1 1 H	Affect on CCR I N Z C
ADC *#opr8i* ADC *opr8a* ADC *opr16a* ADC *oprx16*,X ADC *oprx8*,X ADC ,X ADC *oprx16*,SP ADC *oprx8*,SP	Add with Carry A ← (A) + (M) + (C)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A9 ii B9 dd C9 hh ll D9 ee ff E9 ff F9 9E D9 ee ff 9E E9 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	↕ 1 1 ↕	– ↕ ↕ ↕
ADD *#opr8i* ADD *opr8a* ADD *opr16a* ADD *oprx16*,X ADD *oprx8*,X ADD ,X ADD *oprx16*,SP ADD *oprx8*,SP	Add without Carry A ← (A) + (M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	AB ii BB dd CB hh ll DB ee ff EB ff FB 9E DB ee ff 9E EB ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	↕ 1 1 ↕	– ↕ ↕ ↕
AIS *#opr8i*	Add Immediate Value (Signed) to Stack Pointer SP ← (SP) + (M)	IMM	A7 ii	2	pp	– 1 1 –	– – – –
AIX *#opr8i*	Add Immediate Value (Signed) to Index Register (H:X) H:X ← (H:X) + (M)	IMM	AF ii	2	pp	– 1 1 –	– – – –
AND *#opr8i* AND *opr8a* AND *opr16a* AND *oprx16*,X AND *oprx8*,X AND ,X AND *oprx16*,SP AND *oprx8*,SP	Logical AND A ← (A) & (M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A4 ii B4 dd C4 hh ll D4 ee ff E4 ff F4 9E D4 ee ff 9E E4 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	0 1 1 –	– ↕ ↕ –
ASL *opr8a* ASLA ASLX ASL *oprx8*,X ASL ,X ASL *oprx8*,SP	Arithmetic Shift Left 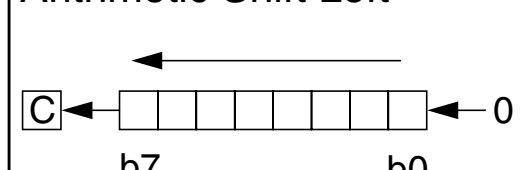 (Same as LSL)	DIR INH INH IX1 IX SP1	38 dd 48 58 68 ff 78 9E 68 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕ 1 1 –	– ↕ ↕ ↕

Table 1. Instruction Set Summary (Sheet 2 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR							
						V	1	1	H	I	N	Z	C
ASR *opr8a* ASRA ASRX ASR *oprx8*,X ASR ,X ASR *oprx8*,SP	Arithmetic Shift Right 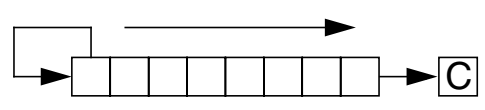 	DIR INH INH IX1 IX SP1	37 dd 47 57 67 ff 77 9E 67 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	↕	↕	↕
BCC *rel*	Branch if Carry Bit Clear (if C = 0)	REL	24 rr	3	pdp	–	1	1	–	–	–	–	–
BCLR *n,opr8a*	Clear Bit n in Memory (Mn ← 0)	DIR (b0) DIR (b1) DIR (b2) DIR (b3) DIR (b4) DIR (b5) DIR (b6) DIR (b7)	11 dd 13 dd 15 dd 17 dd 19 dd 1B dd 1D dd 1F dd	4 4 4 4 4 4 4 4	prwp prwp prwp prwp prwp prwp prwp prwp	–	1	1	–	–	–	–	–
BCS *rel*	Branch if Carry Bit Set (if C = 1) (Same as BLO)	REL	25 rr	3	pdp	–	1	1	–	–	–	–	–
BEQ *rel*	Branch if Equal (if Z = 1)	REL	27 rr	3	pdp	–	1	1	–	–	–	–	–
BGE *rel*	Branch if Greater Than or Equal To (if N ⊕ V = 0) (Signed)	REL	90 rr	3	pdp	–	1	1	–	–	–	–	–
BGT *rel*	Branch if Greater Than (if Z ∣ (N ⊕ V) = 0) (Signed)	REL	92 rr	3	pdp	–	1	1	–	–	–	–	–
BHCC *rel*	Branch if Half Carry Bit Clear (if H = 0)	REL	28 rr	3	pdp	–	1	1	–	–	–	–	–
BHCS *rel*	Branch if Half Carry Bit Set (if H = 1)	REL	29 rr	3	pdp	–	1	1	–	–	–	–	–
BHI *rel*	Branch if Higher (if C ∣ Z = 0)	REL	22 rr	3	pdp	–	1	1	–	–	–	–	–
BHS *rel*	Branch if Higher or Same (if C = 0) (Same as BCC)	REL	24 rr	3	pdp	–	1	1	–	–	–	–	–
BIH *rel*	Branch if IRQ Pin High (if IRQ pin = 1)	REL	2F rr	3	pdp	–	1	1	–	–	–	–	–
BIL *rel*	Branch if IRQ Pin Low (if IRQ pin = 0)	REL	2E rr	3	pdp	–	1	1	–	–	–	–	–
BIT #*opr8i* BIT *opr8a* BIT *opr16a* BIT *oprx16*,X BIT *oprx8*,X BIT ,X BIT *oprx16*,SP BIT *oprx8*,SP	Bit Test (A) & (M) (CCR Updated but Operands Not Changed)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A5 ii B5 dd C5 hh ll D5 ee ff E5 ff F5 9E D5 ee ff 9E E5 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	0	1	1	–	–	↕	↕	–
BLE *rel*	Branch if Less Than or Equal To (if Z ∣ (N ⊕ V) = 1) (Signed)	REL	93 rr	3	pdp	–	1	1	–	–	–	–	–
BLO *rel*	Branch if Lower (if C = 1) (Same as BCS)	REL	25 rr	3	pdp	–	1	1	–	–	–	–	–
BLS *rel*	Branch if Lower or Same (if C ∣ Z = 1)	REL	23 rr	3	pdp	–	1	1	–	–	–	–	–
BLT *rel*	Branch if Less Than (if N ⊕ V = 1) (Signed)	REL	91 rr	3	pdp	–	1	1	–	–	–	–	–

Table 1. Instruction Set Summary (Sheet 3 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR	
						V 1 1 H	I N Z C
BMC *rel*	Branch if Interrupt Mask Clear (if I = 0)	REL	`2C rr`	3	`pdp`	– 1 1 –	– – – –
BMI *rel*	Branch if Minus (if N = 1)	REL	`2B rr`	3	`pdp`	– 1 1 –	– – – –
BMS *rel*	Branch if Interrupt Mask Set (if I = 1)	REL	`2D rr`	3	`pdp`	– 1 1 –	– – – –
BNE *rel*	Branch if Not Equal (if Z = 0)	REL	`26 rr`	3	`pdp`	– 1 1 –	– – – –
BPL *rel*	Branch if Plus (if N = 0)	REL	`2A rr`	3	`pdp`	– 1 1 –	– – – –
BRA *rel*	Branch Always (if I = 1)	REL	`20 rr`	3	`pdp`	– 1 1 –	– – – –

BRCLR *n*,*opr8a*,*rel*	Branch if Bit *n* in Memory Clear (if (Mn) = 0)	DIR (b0)
		DIR (b1)
		DIR (b2)
		DIR (b3)
		DIR (b4)
		DIR (b5)
		DIR (b6)
		DIR (b7)
			`01 dd rr`
			`03 dd rr`
			`05 dd rr`
			`07 dd rr`
			`09 dd rr`
			`0B dd rr`
			`0D dd rr`
			`0F dd rr`
				5
				5
				5
				5
				5
				5
				5
				5
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
						– 1 1 –	– – – ↕

BRN *rel*	Branch Never (if I = 0)	REL	`21 rr`	3	`pdp`	– 1 1 –	– – – –

BRSET *n*,*opr8a*,*rel*	Branch if Bit *n* in Memory Set (if (Mn) = 1)	DIR (b0)
		DIR (b1)
		DIR (b2)
		DIR (b3)
		DIR (b4)
		DIR (b5)
		DIR (b6)
		DIR (b7)
			`00 dd rr`
			`02 dd rr`
			`04 dd rr`
			`06 dd rr`
			`08 dd rr`
			`0A dd rr`
			`0C dd rr`
			`0E dd rr`
				5
				5
				5
				5
				5
				5
				5
				5
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
					`prpdp`
						– 1 1 –	– – – ↕

BSET *n*,*opr8a*	Set Bit *n* in Memory (Mn ← 1)	DIR (b0)
		DIR (b1)
		DIR (b2)
		DIR (b3)
		DIR (b4)
		DIR (b5)
		DIR (b6)
		DIR (b7)
			`10 dd`
			`12 dd`
			`14 dd`
			`16 dd`
			`18 dd`
			`1A dd`
			`1C dd`
			`1E dd`
				4
				4
				4
				4
				4
				4
				4
				4
					`prwp`
					`prwp`
					`prwp`
					`prwp`
					`prwp`
					`prwp`
					`prwp`
					`prwp`
						– 1 1 –	– – – –

BSR *rel*	Branch to Subroutine PC ← (PC) + \$0002 push (PCL); SP ← (SP) – \$0001 push (PCH); SP ← (SP) – \$0001 PC ← (PC) + *rel*	REL	`AD rr`	4	`pssp`	– 1 1 –	– – – –

CBEQ *opr8a*,*rel*
CBEQA #*opr8i*,*rel*
CBEQX #*opr8i*,*rel*
CBEQ *oprx8*,X+,*rel*
CBEQ ,X+,*rel*
CBEQ *oprx8*,SP,*rel*
	Compare and... Branch if (A) = (M)
	Branch if (A) = (M)
	Branch if (X) = (M)
	Branch if (A) = (M)
	Branch if (A) = (M)
	Branch if (A) = (M)
		DIR
		IMM
		IMM
		IX1+
		IX+
		SP1
			`31 dd rr`
			`41 ii rr`
			`51 ii rr`
			`61 ff rr`
			`71 rr`
			`9E 61 ff rr`
				5
				4
				4
				5
				4
				6
					`pprdp`
					`ppdp`
					`ppdp`
					`pprdp`
					`prdp`
					`ppprdp`
						– 1 1 –	– – – –

CLC	Clear Carry Bit (C ← 0)	INH	`98`	1	`p`	– 1 1 –	– – – 0
CLI	Clear Interrupt Mask Bit (I ← 0)	INH	`9A`	2	`pd`	– 1 1 –	0 – – –

Table 1. Instruction Set Summary (Sheet 4 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR V 1 1 H	Affect on CCR I N Z C
CLR *opr8a* CLRA CLRX CLRH CLR *oprx8*,X CLR ,X CLR *oprx8*,SP	Clear M ← $00 A ← $00 X ← $00 H ← $00 M ← $00 M ← $00 M ← $00	DIR INH INH INH IX1 IX SP1	3F dd 4F 5F 8C 6F ff 7F 9E 6F ff	3 1 1 1 3 2 4	pwp p p p ppw pw pppw	0 1 1 –	– 0 1 –
CMP #*opr8i* CMP *opr8a* CMP *opr16a* CMP *oprx16*,X CMP *oprx8*,X CMP ,X CMP *oprx16*,SP CMP *oprx8*,SP	Compare Accumulator with Memory A – M (CCR Updated But Operands Not Changed)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A1 ii B1 dd C1 hh ll D1 ee ff E1 ff F1 9E D1 ee ff 9E E1 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	↕ 1 1 –	– ↕ ↕ ↕
COM *opr8a* COMA COMX COM *oprx8*,X COM ,X COM *oprx8*,SP	Complement M ← (M̄)= $FF – (M) (One's Complement) A ← (Ā) = $FF – (A) X ← (X̄) = $FF – (X) M ← (M̄) = $FF – (M) M ← (M̄) = $FF – (M) M ← (M̄) = $FF – (M)	DIR INH INH IX1 IX SP1	33 dd 43 53 63 ff 73 9E 63 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	0 1 1 –	– ↕ ↕ 1
CPHX #*opr* CPHX *opr*	Compare Index Register (H:X) with Memory (H:X) – (M:M + $0001) (CCR Updated But Operands Not Changed)	IMM DIR	65 ii jj 75 dd	3 4	ppp prrp	↕ 1 1 –	– ↕ ↕ ↕
CPX #*opr8i* CPX *opr8a* CPX *opr16a* CPX *oprx16*,X CPX *oprx8*,X CPX ,X CPX *oprx16*,SP CPX *oprx8*,SP	Compare X (Index Register Low) with Memory X – M (CCR Updated But Operands Not Changed)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A3 ii B3 dd C3 hh ll D3 ee ff E3 ff F3 9E D3 ee ff 9E E3 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	↕ 1 1 –	– ↕ ↕ ↕
DAA	Decimal Adjust Accumulator After ADD or ADC of BCD Values	INH	72	2	pp	U 1 1 –	– ↕ ↕ ↕
DBNZ *opr8a*,*rel* DBNZA *rel* DBNZX *rel* DBNZ *oprx8*,X,*rel* DBNZ ,X,*rel* DBNZ *oprx8*,SP,*rel*	Decrement A, X, or M and Branch if Not Zero (if (result) ≠ 0) DBNZX Affects X Not H	DIR INH INH IX1 IX SP1	3B dd rr 4B rr 5B rr 6B ff rr 7B rr 9E 6B ff rr	5 3 3 5 4 6	pprwp pdp pdp pprwp prwp ppprwp	– 1 1 –	– – – –
DEC *opr8a* DECA DECX DEC *oprx8*,X DEC ,X DEC *oprx8*,SP	Decrement M ← (M) – $01 A ← (A) – $01 X ← (X) – $01 M ← (M) – $01 M ← (M) – $01 M ← (M) – $01	DIR INH INH IX1 IX SP1	3A dd 4A 5A 6A ff 7A 9E 6A ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕ 1 1 –	– ↕ ↕ –
DIV	Divide A ← (H:A)÷(X); H ← Remainder	INH	52	7	pdpdddd	– 1 1 –	– – ↕ ↕

Table 1. Instruction Set Summary (Sheet 5 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR V	1	1	H	I	N	Z	C
EOR *#opr8i* EOR *opr8a* EOR *opr16a* EOR *oprx16*,X EOR *oprx8*,X EOR ,X EOR *oprx16*,SP EOR *oprx8*,SP	Exclusive OR Memory with Accumulator A ← (A ⊕ M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A8 ii B8 dd C8 hh ll D8 ee ff E8 ff F8 9E D8 ee ff 9E E8 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	0	1	1	–	–	↕	↕	–
INC *opr8a* INCA INCX INC *oprx8*,X INC ,X INC *oprx8*,SP	Increment M ← (M) + $01 A ← (A) + $01 X ← (X) + $01 M ← (M) + $01 M ← (M) + $01 M ← (M) + $01	DIR INH INH IX1 IX SP1	3C dd 4C 5C 6C ff 7C 9E 6C ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	↕	↕	–
JMP *opr8a* JMP *opr16a* JMP *oprx16*,X JMP *oprx8*,X JMP ,X	Jump PC ← Jump Address	DIR EXT IX2 IX1 IX	BC dd CC hh ll DC ee ff EC ff FC	2 3 4 3 2	pp ppp ppdp pdp pp	–	1	1	–	–	–	–	–
JSR *opr8a* JSR *opr16a* JSR *oprx16*,X JSR *oprx8*,X JSR ,X	Jump to Subroutine PC ← (PC) + *n* (*n* = 1, 2, or 3) Push (PCL); SP ← (SP) – $0001 Push (PCH); SP ← (SP) – $0001 PC ← Unconditional Address	DIR EXT IX2 IX1 IX	BD dd CD hh ll DD ee ff ED ff FD	4 5 6 5 4	pssp ppssp ppssdp pssdp pssp	–	1	1	–	–	–	–	–
LDA *#opr8i* LDA *opr8a* LDA *opr16a* LDA *oprx16*,X LDA *oprx8*,X LDA ,X LDA *oprx16*,SP LDA *oprx8*,SP	Load Accumulator from Memory A ← (M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A6 ii B6 dd C6 hh ll D6 ee ff E6 ff F6 9E D6 ee ff 9E E6 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	0	1	1	–	–	↕	↕	–
LDHX *#opr* LDHX *opr*	Load Index Register (H:X) H:X ← (M:M + $0001)	IMM DIR	45 ii jj 55 dd	3 4	ppp prrp	0	1	1	–	–	↕	↕	–
LDX *#opr8i* LDX *opr8a* LDX *opr16a* LDX *oprx16*,X LDX *oprx8*,X LDX ,X LDX *oprx16*,SP LDX *oprx8*,SP	Load X (Index Register Low) from Memory X ← (M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	AE ii BE dd CE hh ll DE ee ff EE ff FE 9E DE ee ff 9E EE ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	0	1	1	–	–	↕	↕	–
LSL *opr8a* LSLA LSLX LSL *oprx8*,X LSL ,X LSL *oprx8*,SP	Logical Shift Left 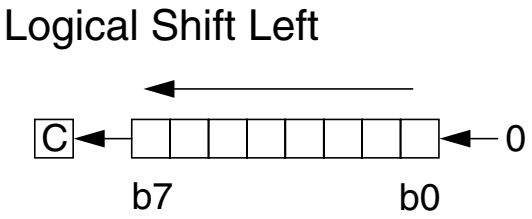 (Same as ASL)	DIR INH INH IX1 IX SP1	38 dd 48 58 68 ff 78 9E 68 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	↕	↕	↕

Table 1. Instruction Set Summary (Sheet 6 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR							
						V	1	1	H	I	N	Z	C
LSR *opr8a* LSRA LSR*X* LSR *oprx8*,X LSR ,X LSR *oprx8*,SP	Logical Shift Right 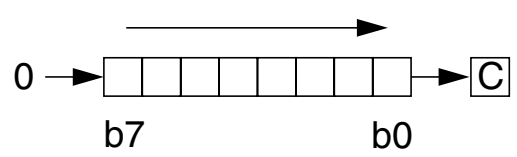	DIR INH INH IX1 IX SP1	34 dd 44 54 64 ff 74 9E 64 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	0	↕	↕
MOV *opr8a*,*opr8a* MOV *opr8a*,X+ MOV #*opr8i*,*opr8a* MOV ,X+,*opr8a*	Move $(M)_{destination}$ ← $(M)_{source}$ In IX+/DIR and DIR/IX+ Modes, H:X ← (H:X) + \$0001	DIR/DIR DIR/IX+ IMM/DIR IX+/DIR	4E dd dd 5E dd 6E ii dd 7E dd	5 4 4 4	prpwp prwp ppwp prwp	0	1	1	–	–	↕	↕	–
MUL	Unsigned multiply X:A ← (X) × (A)	INH	42	5	ppddd	–	1	1	0	–	–	–	0
NEG *opr8a* NEGA NEGX NEG *oprx8*,X NEG ,X NEG *oprx8*,SP	Negate (Two's Complement) M ← – (M) = \$00 – (M) A ← – (A) = \$00 – (A) X ← – (X) = \$00 – (X) M ← – (M) = \$00 – (M) M ← – (M) = \$00 – (M) M ← – (M) = \$00 – (M)	DIR INH INH IX1 IX SP1	30 dd 40 50 60 ff 70 9E 60 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	↕	↕	↕
NOP	No Operation — Uses 1 Bus Cycle	INH	9D	1	p	–	1	1	–	–	–	–	–
NSA	Nibble Swap Accumulator A ← (A[3:0]:A[7:4])	INH	62	3	ppd	–	1	1	–	–	–	–	–
ORA #*opr8i* ORA *opr8a* ORA *opr16a* ORA *oprx16*,X ORA *oprx8*,X ORA ,X ORA *oprx16*,SP ORA *oprx8*,SP	Inclusive OR Accumulator and Memory A ← (A) | (M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	AA ii BA dd CA hh ll DA ee ff EA ff FA 9E DA ee ff 9E EA ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	0	1	1	–	–	↕	↕	–
PSHA	Push Accumulator onto Stack Push (A); SP ← (SP) – \$0001	INH	87	2	ps	–	1	1	–	–	–	–	–
PSHH	Push H (Index Register High) onto Stack Push (H); SP ← (SP) – \$0001	INH	8B	2	ps	–	1	1	–	–	–	–	–
PSHX	Push X (Index Register Low) onto Stack Push (X); SP ← (SP) – \$0001	INH	89	2	ps	–	1	1	–	–	–	–	–
PULA	Pull Accumulator from Stack SP ← (SP + \$0001); Pull (A)	INH	86	2	pu	–	1	1	–	–	–	–	–
PULH	Pull H (Index Register High) from Stack SP ← (SP + \$0001); Pull (H)	INH	8A	2	pu	–	1	1	–	–	–	–	–
PULX	Pull X (Index Register Low) from Stack SP ← (SP + \$0001); Pull (X)	INH	88	2	pu	–	1	1	–	–	–	–	–

Table 1. Instruction Set Summary (Sheet 7 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR V	1	1	H	I	N	Z	C
ROL *opr8a* ROLA ROLX ROL *oprx8*,X ROL ,X ROL *oprx8*,SP	Rotate Left through Carry 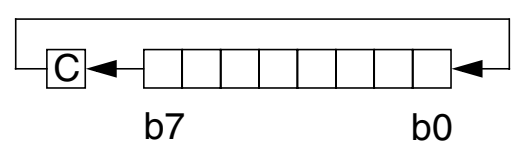 	DIR INH INH IX1 IX SP1	39 dd 49 59 69 ff 79 9E 69 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	↕	↕	↕
ROR *opr8a* RORA RORX ROR *oprx8*,X ROR ,X ROR *oprx8*,SP	Rotate Right through Carry 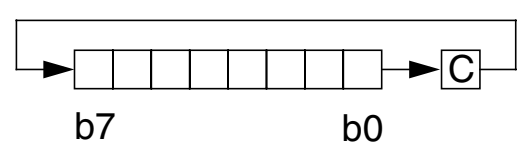 	DIR INH INH IX1 IX SP1	36 dd 46 56 66 ff 76 9E 66 ff	4 1 1 4 3 5	prwp p p pprw prw ppprw	↕	1	1	–	–	↕	↕	↕
RSP	Reset Stack Pointer (Low Byte) SPL ← $FF (High Byte Not Affected)	INH	9C	1	p	–	1	1	–	–	–	–	–
RTI	Return from Interrupt SP ← (SP) + $0001; Pull (CCR) SP ← (SP) + $0001; Pull (A) SP ← (SP) + $0001; Pull (X) SP ← (SP) + $0001; Pull (PCH) SP ← (SP) + $0001; Pull (PCL)	INH	80	7	puuuuup	↕	1	1	↕	↕	↕	↕	↕
RTS	Return from Subroutine SP ← SP + $0001; Pull (PCH) SP ← SP + $0001; Pull (PCL)	INH	81	4	puup	–	1	1	–	–	–	–	–
SBC #*opr8i* SBC *opr8a* SBC *opr16a* SBC *oprx16*,X SBC *oprx8*,X SBC ,X SBC *oprx16*,SP SBC *oprx8*,SP	Subtract with Carry A ← (A) – (M) – (C)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A2 ii B2 dd C2 hh ll D2 ee ff E2 ff F2 9E D2 ee ff 9E E2 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	↕	1	1	–	–	↕	↕	↕
SEC	Set Carry Bit (C ← 1)	INH	99	1	p	–	1	1	–	–	–	–	1
SEI	Set Interrupt Mask Bit (I ← 1)	INH	9B	2	pd	–	1	1	–	1	–	–	–
STA *opr8a* STA *opr16a* STA *oprx16*,X STA *oprx8*,X STA ,X STA *oprx16*,SP STA *oprx8*,SP	Store Accumulator in Memory M ← (A)	DIR EXT IX2 IX1 IX SP2 SP1	B7 dd C7 hh ll D7 ee ff E7 ff F7 9E D7 ee ff 9E E7 ff	3 4 4 3 2 5 4	pwp ppwp pppw ppw pw ppppw pppw	0	1	1	–	–	↕	↕	–
STHX *opr*	Store H:X (Index Reg.) (M:M + $0001) ← (H:X)	DIR	35 dd	4	pwwp	0	1	1	–	–	↕	↕	–
STOP	Enable Interrupts: Stop Processing Refer to MCU Documentation I bit ← 0; Stop Processing	INH	8E	1	p	–	1	1	–	0	–	–	–

Table 1. Instruction Set Summary (Sheet 8 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR V 1 1 H	I N Z C
STX *opr8a* STX *opr16a* STX *oprx16*,X STX *oprx8*,X STX ,X STX *oprx16*,SP STX *oprx8*,SP	Store X (Low 8 Bits of Index Register) in Memory M ← (X)	DIR EXT IX2 IX1 IX SP2 SP1	BF dd CF hh ll DF ee ff EF ff FF 9E DF ee ff 9E EF ff	3 4 4 3 2 5 4	pwp ppwp pppw ppw pw ppppw pppw	0 1 1 –	– ↕ ↕ –
SUB #*opr8i* SUB *opr8a* SUB *opr16a* SUB *oprx16*,X SUB *oprx8*,X SUB ,X SUB *oprx16*,SP SUB *oprx8*,SP	Subtract A ← (A) – (M)	IMM DIR EXT IX2 IX1 IX SP2 SP1	A0 ii B0 dd C0 hh ll D0 ee ff E0 ff F0 9E D0 ee ff 9E E0 ff	2 3 4 4 3 2 5 4	pp prp pprp pppr ppr pr ppppr pppr	↕ 1 1 –	– ↕ ↕ ↕
SWI	Software Interrupt PC ← (PC) + $0001 Push (PCL); SP ← (SP) – $0001 Push (PCH); SP ← (SP) – $0001 Push (X); SP ← (SP) – $0001 Push (A); SP ← (SP) – $0001 Push (CCR); SP ← (SP) – $0001 I ← 1; PCH ← Interrupt Vector High Byte PCL ← Interrupt Vector Low Byte	INH	83	9	psssssvvp	– 1 1 –	1 – – –
TAP	Transfer Accumulator to CCR CCR ← (A)	INH	84	2	pd	↕ 1 1 ↕	↕ ↕ ↕ ↕
TAX	Transfer Accumulator to X (Index Register Low) X ← (A)	INH	97	1	p	– 1 1 –	– – – –
TPA	Transfer CCR to Accumulator A ← (CCR)	INH	85	1	p	– 1 1 –	– – – –
TST *opr8a* TSTA TSTX TST *oprx8*,X TST ,X TST *oprx8*,SP	Test for Negative or Zero (M) – $00 (A) – $00 (X) – $00 (M) – $00 (M) – $00 (M) – $00	DIR INH INH IX1 IX SP1	3D dd 4D 5D 6D ff 7D 9E 6D ff	3 1 1 3 2 4	prp p p ppr pr pppr	0 1 1 –	– ↕ ↕ –
TSX	Transfer SP to Index Reg. H:X ← (SP) + $0001	INH	95	2	pp	– 1 1 –	– – – –
TXA	Transfer X (Index Reg. Low) to Accumulator A ← (X)	INH	9F	1	p	– 1 1 –	– – – –

Table 1. Instruction Set Summary (Sheet 9 of 9)

Source Form	Operation	Address Mode	Object Code	Cycles	Cyc-by-Cyc Details	Affect on CCR V 1 1 H	I N Z C
TXS	Transfer Index Reg. to SP SP ← (H:X) – $0001	INH	94	2	pp	– 1 1 –	– – – –
WAIT	Enable Interrupts; Wait for Interrupt I bit ← 0; Halt CPU	INH	8F	1	p	– 1 1 –	0 – – –

Object Code:

- dd — Direct address of operand
- ee ff — High and low bytes of offset in indexed, 16-bit offset addressing
- ff — Offset byte in indexed, 8-bit offset addressing
- hh ll — High and low bytes of operand address in extended addressing
- ii — Immediate operand byte
- ii jj — 16-bit immediate operand for H:X
- rr — Relative program counter offset byte

Addressing Modes:

- DIR — Direct addressing mode
- EXT — Extended addressing mode
- IMM — Immediate addressing mode
- INH — Inherent addressing mode
- IX — Indexed, no offset addressing mode
- IX1 — Indexed, 8-bit offset addressing mode
- IX2 — Indexed, 16-bit offset addressing mode
- IX+ — Indexed, no offset, post increment addressing mode
- IX1+ — Indexed, 8-bit offset, post increment addressing mode
- REL — Relative addressing mode
- SP1 — Stack pointer, 8-bit offset addressing mode
- SP2 — Stack pointer 16-bit offset addressing mode

CCR Bits, Effects:

- V — Overflow bit
- H — Half-carry bit
- I — Interrupt mask
- N — Negative bit
- Z — Zero bit
- C — Carry/borrow bit
- ↕ — Set or cleared
- – — Not affected
- U — Undefined

Operation Symbols:

- A — Accumulator
- CCR — Condition code register
- H — Index register high byte
- M — Memory location
- *n* — Any bit
- *opr* — Operand (one or two bytes)
- PC — Program counter
- PCH — Program counter high byte
- PCL — Program counter low byte
- *rel* — Relative program counter offset byte
- SP — Stack pointer
- X — Index register low byte
- & — Logical AND
- | — Logical OR
- ⊕ — Logical EXCLUSIVE OR
- ( ) — Contents of
- –( ) — Negation (two's complement)
- # — Immediate value
- « — Sign extend
- ← — Loaded with
- ? — If
- : — Concatenated with

Cycle-by-Cycle Codes:

- d — Dummy duplicate of the previous p, r, or s cycle. d is always a read cycle so sd is a stack write followed by a read of the address pointed-to by the updated stack pointer
- p — Program fetch; read from next consecutive location in program memory
- r — Read 8-bit operand
- s — Push (write) one byte onto stack
- u — Pop (read) one byte from stack
- v — Read vector from $FFxx (high byte first)
- w — Write 8-bit operand

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