## AN14723

# Establishing ISP Mode Communication with KW45B41Z Using KW45B41Z-LOC Board

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**Application note** 

#### **Document information**

Information	Content
Keywords	AN14723, KW45, KW45B41Z, KW45-LOC, ISP, UART, I2C, SPI, CAN, BusPal
Abstract	This application note describes the necessary steps to establish communication with a KW45B41Z microcontroller in ISP mode, referred to as target MCU, through each one of the supported interfaces, using KW45B41Z-LOC board.



#### Establishing ISP Mode Communication with KW45B41Z Using KW45B41Z-LOC Board

#### 1 Introduction

The KW45B41Z microcontroller contains a ROM bootloader, which is boot code resident in the read-only memory (ROM). The ROM bootloader begins its execution when the Cortex-M33 processor is released from reset, and can follow different paths. This document focuses on the in-system programming (ISP) path.

The ISP utility operates over a serial connection on the MCUs. Users can use host tools to upload/download application code via the bootloader.

This application note outlines the steps required to establish communication with the KW45B41Z microcontroller in ISP mode (referred to as the target MCU). The document demonstrates how to achieve the interface-based communication using the KW45B41Z-LOC board through each of the supported interfaces (UART, I2C, SPI, and CAN).

## 2 Entering ISP mode

For the ROM bootloader to follow the ISP path, BOOT\_CONFIG pin (PTA4) must be active. To do so, perform the following steps:

- 1. Disconnect the board from all power sources.
- 2. Close JP16.
- 3. Keep the SW4 button pressed while connecting the board to the host USB port.
- 4. Reconnect any external power supply, if needed.
- 5. Release the SW4 button.

After following these steps, the KW45B41Z microcontroller enters the ISP mode.

#### 3 Software and tools

In this document:

- The blhost utility of the SPSDK software is used when I2C or SPI protocols are selected as the communication interface.
- The standalone blhost application is used when a CAN interface is selected as the communication interface. SPSDK currently does not support CAN.

Table 1 shows the versions of the tools used for the current document.

Table 1. Tool versions

Tool	Version
SPSDK	2.6.0
Blhost	2.6.7

#### 3.1 BusPal

BusPal is an embedded software tool available as a companion to the blhost application. It acts as a bus translator between blhost and the target device. It connects to the blhost application over a UART connection, and connects to the target device over an I2C, SPI, or a CAN connection. It assists the blhost application in performing commands and responses from the target device.

The source code for BusPal is provided with the Kinetis bootloader release. The source code is only available for selected platforms, but it can be customized to run on other platforms.

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For more details on the BusPal software tool and the MCU bootloader for NXP MCUs, refer to MCU Bootloader for NXP Microcontrollers.

### 4 Establishing communication

This section describes how to establish communication between the host computer and the target MCU using the UART, I2C, SPI, or CAN interface. A host-side command-line tool (for example, blhost) can be used to communicate with the target MCU directly over a UART connection. To enable I2C, SPI, or CAN communication between the host computer and the target MCU, two components are required:

- A bridge, such as BusPal, created using an external device.
- · A host-side command-line tool, such as blhost, to send commands from the host.

The user can use one of the following NXP MCUs to create a BusPal bridge:

- MKL25Z
- MKV46
- MK65F
- MCXW71
- MCXA156

To learn more about BusPal devices and how to program the BusPal firmware, refer to <u>BusPal Application for FRDM MCX Families</u>.

**Note:** The current document only includes examples with MKL25Z, MCXW71, and MCXA156 MCUs used as BusPal bridge devices.

To make the MCU ready to receive ISP commands using the host-side tool, follow the steps described in Section 2 and the following subsections.

#### 4.1 Universal asynchronous receiver/transmitter (UART)

To communicate with the target MCU via UART, no external hardware or modifications are needed. Verify that the JP13 and JP14 jumpers are placed in their default 1-2 position.

Figure 1 shows the response by the target MCU after receiving ISP command via UART interface.

```
(venv) C:\Users\nxf87131\Documents\SPSDK\git\spsdk\venv>blhost -p COM17 get-property 1
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
Figure 1. Response from target MCU after ISP command via UART
```

## 4.2 Inter-integrated circuit (I2C)

To communicate with the target MCU using the I2C, JP24 should be placed in the 2-3 position, as shown in Figure 2.

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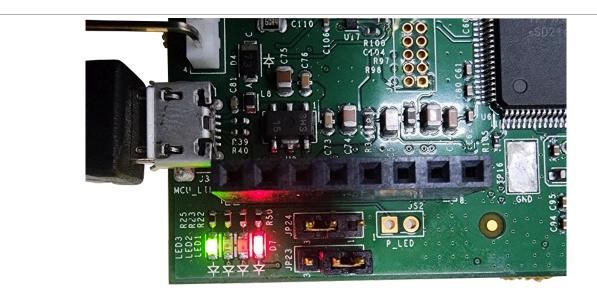


Figure 2. KW45B41Z-LOC board with JP24 in 2-3 position

For I2C interface, an external device is needed to act as a bridge between the host and the target MCU. The user should use the pins described in Table 2, depending on the BusPal bridge device selected.

Table 2 12C connection setup

	Table 11 12 Commoder Cotap						
Signal	Signal	Target MCU		MKL25Z BusPal		MCXA156 BusPal	
	· ·	MCUnin	KW45-LOC connector			FRDM-MCXA156 connector	
	LPI2C_SCL	PTB5	J2, pin 5	J1, pin 14	J2, pin 1	J5, pin 5	
Ī	LPI2C_SDA	PTB4	J2, pin 6	J1, pin 16	J2, pin 2	J5, pin 6	

Figure 3 shows the response by the target MCU after receiving ISP command via I2C interface.

```
C:\nxp>blhost -b i2c -p COM132 get-property 1
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

Figure 3. Response from target MCU after ISP command via I2C

#### 4.3 Serial peripheral interface (SPI)

To communicate via SPI with the target MCU, no modifications in the KW45B41Z-LOC board are needed. However, an external device is needed to act as a bridge between the host and the target MCU. Use the pins described in Table 3, depending on the BusPal bridge device selected.

Table 3. Connection setup for SPI communication.

Signal	Target MCU		MKL25Z BusPal	MCXW71 BusPal	MCXA156 BusPal
	MCU pin				FRDM-MCXA156 connector
LPSPI_PCS0	PTB0	J1, pin 3	J2, pin 6	J2, pin 8	J6, pin 3

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Table 3. Connection setup for SPI communication....continued

Signal	Target MCU		MKL25Z BusPal		MCXA156 BusPal
		KW45-LOC connector	FRDM-KL25Z connector		FRDM-MCXA156 connector
LPSPI_SIN	PTB1	J1, pin 5	J2, pin 8	J2, pin 7	J6, pin 6
LPSPI_SCK	PTB2	J1, pin 4	J2, pin 12	J2, pin 5	J6, pin 4
LPSPI_SOUT	PTB3	J1, pin 6	J2, pin 10	J2, pin 6	J6, pin 5

Figure 4 shows the response by the target MCU after receiving ISP command via SPI interface.

```
C:\nxp>blhost -b spi -p COM132 get-property 1
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

Figure 4. Response from target MCU after ISP command via SPI

Figure 5. Response from target MCU after ISP command via CAN

#### 4.4 Controller area network (CAN)

To communicate with the target MCU via CAN, no modifications are needed on the KW45B41Z-LOC board. However, an external 12 V power supply needs to be connected to J9, which provides power for the CAN transceiver.

For CAN interface, an external device is needed to act as a bridge between the host and the target MCU. Use the pins described in <u>Table 4</u>.

Table 4. Connection setup for CAN communication.

Signal	Target MCU		MCXW71 BusPal	MCXA156 BusPal
	MCU pin			FRDM-MCXA156 connector
CAN0_TX	PTC4	J10, pin 1	J21, pin 1	J22, pin 2
CAN0_RX	PTC5	J10, pin 2	J21, pin 2	J22, pin 4

Figure 5 shows the response by the target MCU after receiving ISP command via CAN interface.

```
C:\Users\nxf87131\Documents\blhost_2.6.7\bin\win>blhost.exe -b can -p COM5 get-property 1
Entering bit bang mode...
Entered BB mode
Ping responded in 1 attempt(s)
Inject command 'get-property'
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

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## 5 Revision history

<u>Table 5</u> summarizes the revisions to this document.

Table 5. Revision history

Document ID	Release date	Description
AN14723 v.1.0	24 June 2025	Initial public release

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