AN14649

KW47-EVK In-System Programming Utility

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Document information

Information	Content
Keywords	AN14649, KW47, ISP mode
Abstract	This document provides steps to boot the KW47 MCU into ISP mode and establish various serial connections to communicate with the MCU.

1 Introduction

The KW47 Microcontroller Unit (MCU) contains a Read-Only Memory (ROM) bootloader, which is a boot code in the ROM. The ROM bootloader starts to execute when the Cortex-M33 core is released from a reset. The bootloader follows different paths. One of them is the In-System Programming (ISP) path. To make the bootloader follow the ISP path, use the ISP utility. The ISP utility operates over a serial connection on the MCU. To upload/download the application code using the bootloader, use the host-side tools.

This document provides steps to boot the KW47 MCU into ISP mode and establish various serial connections to communicate with the MCU. To demonstrate the ISP functionality, use the KW47-EVK board as the KW47 MCU platform. The KW47 MCU is called the target MCU at some places in the document.

2 Entering ISP mode

The KW47 MCU has two different ways to enter the ISP mode. One uses the designated button on the KW47-EVK board, which asserts the appropriate signal for the ROM bootloader to boot in the ISP mode while powering the board. The KW47 MCU can follow the ISP path using the software method, which you can use while the MCU is running.

2.1 ISP entry via HW

To make the bootloader follow the ISP path (to boot the KW47 MCU into ISP mode), the BOOT_CFG (PTA4) pin of the MCU must be active. To activate this pin and boot the target MCU in the ISP mode, follow these steps:

1. Disconnect the KW47-EVK board from all power sources.
2. Press and hold the SW4 (BOOT_CONFIG) button while connecting the board to the host computer USB port using the J14 USB Type-C connector.
3. Release the SW4 (BOOT_CONFIG) button. The KW47 boots into ISP mode.
4. Connect any external power supply, if needed.

2.2 ISP entry via SW

To enter the ISP mode using software, assert the FORCECFG bit from the CMC[FM] register and perform an SW reset. When the device resets, it enters the ISP mode.

3 Software and tools

This document uses the following tools:

- Use the blhost utility of the Secure Provisioning Software Development Kit (SPSDK) when selecting the Inter-Integrated Circuit (I2C) or Serial Peripheral Interface (SPI) protocols as the communication interface.
- Use the standalone blhost application when selecting the Controller Area Network (CAN) interface as the communication interface, because the current version of SPSDK does not support CAN yet.

Table 1 shows the versions of the tools used in this document.

Table 1. Tool versions

Tool	Version
SPSDK	2.6.0
blhost	2.6.7

3.1 BusPal

BusPal is an embedded software tool available together with the blhost application. It acts as a bus translator between blhost and the target device. It connects to the blhost application over a Universal Asynchronous Receiver/Transmitter (UART) connection, and it connects to the target device over an I2C, SPI, or CAN connection. It helps the blhost application to perform commands and responses from the target device.

The source code for BusPal comes together with the Kinetis bootloader release. The source code is available only for selected platforms, but you can customize it to run on other platforms.

For more details on the BusPal software tool and the MCU bootloader for NXP MCUs, see MCU Bootloader for NXP Microcontrollers.

4 Establishing communication

This section describes how to establish the communication between the host computer and the target MCU using the UART, I2C, SPI, or CAN interface. Use a host-side command-line tool (for example, blhost) to communicate with the target MCU directly over a UART connection. To enable the I2C, SPI, or CAN communication between the host computer and the target MCU, create a bridge (for example, BusPal) using an external device, along with a host-side command-line tool (for example, blhost).

Use one of the following NXP MCUs to create a BusPal bridge:

- MKL25Z
- MKV46
- MK65F
- MCX W71
- MCX A156

For more information about the BusPal devices and how to program the BusPal firmware, see NXP Application Code Hub.

Note: *The current document includes only examples with the MKL25Z, MCX W71, and MCX A156 MCUs, used as BusPal bridge devices.*

4.1 Using UART interface

To communicate with the target MCU using the UART interface, you do not need any external hardware or modifications. To establish a UART connection between the host computer and the KW47 MCU (KW47-EVK board), boot the MCU in the ISP mode, as explained in Section 2. The target MCU starts to receive ISP commands using the host-side tool.

Figure 1 shows the response from the target MCU after running the ISP command using the UART interface.

```
C:\nxp>blhost -p COM177 get-property 1
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

Figure 1. Running ISP command using UART interface

4.2 Using I2C interface

To communicate with the target MCU using the Inter-Integrated Circuit (I2C) interface, create a BusPal bridge (using an external device) between the host computer and the target MCU. You can use devices, such as MCX W71 or MCX A156, as BusPal bridge devices for the I2C communication.

To establish an I2C connection between the host computer and the target MCU using MKL25Z (FRDM-KL25Z board), MCX W71 (FRDM-MCXW71 board), or MCX A156 (FRDM-MCXA156 board) as a bridge device, perform the following steps:

1. Boot the target MCU into ISP, as explained in Section 2.
2. Set up an I2C connection between the KW47-EVK board and the FRDM-KL25Z/FRDM-MCXW71/FRDM-MCXA156 board, as shown in Table 2.

Table 2. I2C connection setup

Signal	Target MCU		MKL25Z BusPal	MCX W71 BusPal	MCX A156 BusPal
	MCU pin	KW47-EVK connector	FRDM-KL25Z connector	FRDM-MCXW71 connector	FRDM-MCXA156 connector
LPI2C_SCL	PTB5	J2, pin 1 / J13, pin 5 / J19, pin 6	J1, pin 14	J2, pin 1	J5, pin 5
LPI2C_SDA	PTB4	J2, pin 3 / J13, pin 6 / J19, pin 8	J1, pin 16	J2, pin 2	J5, pin 6

After following the above steps, the target MCU starts to receive the ISP commands using the host-side tool. Figure 2 shows the response from the target MCU after running the ISP command using the I2C interface.

```
C:\nxp>blhost -b i2c -p COM132 get-property 1
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

Figure 2. Running ISP command using I2C interface

4.3 Using SPI

To communicate with the target MCU using the SPI, create a BusPal bridge (using an external device) between the host computer and the target MCU. You can use the MCX W71 or MCX A156 devices as a BusPal bridge for the SPI communication.

To establish an SPI connection between the host computer and the target MCU using MKL25Z (FRDM-KL25Z board), MCX W71 (FRDM-MCXW71 board), or MCX A156 (FRDM-MCXA156 board) as a bridge device, perform the following steps:

1. Boot the target MCU into the ISP mode, as explained in Section 2.
2. Set up an SPI connection between the KW47-EVK board and the FRDM-KL25Z/FRDM-MCXW71/FRDM-MCXA156 board, as shown in Table 3.

Table 3. SPI connection setup

Signal	Target MCU		MKL25Z BusPal	MCX W71 BusPal	MCX A156 BusPal
	MCU pin	KW47-EVK connector	FRDM-KL25Z connector	FRDM-MCXW71 connector	FRDM-MCXA156 connector
LPSPI_PCS0	PTB0	J2, pin 15 / J12, pin 3	J2, pin 6	J2, pin 8	J6, pin 3
LPSPI_SIN	PTB1	J2, pin 11 / J12, pin 5	J2, pin 8	J2, pin 7	J6, pin 6

Table 3. SPI connection setup*...continued*

Signal	Target MCU		MKL25Z BusPal	MCX W71 BusPal	MCX A156 BusPal
	MCU pin	KW47-EVK connector	FRDM-KL25Z connector	FRDM-MCXW71 connector	FRDM-MCXA156 connector
LPSPI_SCK	PTB2	J2, pin 9 / J12, pin 4	J2, pin 12	J2, pin 5	J6, pin 4
LPSPI_SOUT	PTB3	J2, pin 13 / J12, pin 6	J2, pin 10	J2, pin 6	J6, pin 5

After following the above steps, the target MCU starts receiving ISP commands using the host-side tool. Figure 3 shows the response from the target MCU after running the ISP command using the SPI interface.

```
C:\nxp>blhost -b spi -p COM132 get-property 1
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

Figure 3. Running ISP command using SPI interface

4.4 Using CAN interface

To communicate with the target MCU using the CAN, you must create a BusPal bridge (using an external device) between the host computer and the target MCU. For the CAN communication, only MCX W71 and MCX A156 MCUs can be used as BusPal bridge devices.

To establish a CAN connection between the host computer and the target MCU while using the MCX W71 (FRDM-MCXW71 board) or MCX A156 (FRDM-MCXA156 board) as a bridge device, follow these steps:

1. Boot the target MCU into ISP, as explained in Section 2. To power on the CAN transceiver in the KW47-EVK board, provide an external 12-V power supply at connector J9.
2. Set up a CAN connection between the KW47-EVK board and the FRDM-MCXW71/FRDM-MCXA156 board, as described in Table 4.

Table 4. CAN connection setup

Signal	Target MCU		MCX W71 BusPal	MCX A156 BusPal
	MCU pin	KW47-EVK connector	FRDM-MCXW71 connector	FRDM-MCXA156 connector
CAN0_TX	PTC4	J10, pin 1	J21, pin 1	J22, pin 2
CAN0_RX	PTC5	J10, pin 2	J21, pin 2	J22, pin 4

After following the above steps, the target MCU starts receiving the ISP commands using the host-side tool. Figure 4 shows the response from the target MCU after running the ISP command using the CAN interface.

```
C:\nxp>blhost.exe -b can -p COM109 get-property 1
Entering bit bang mode...
Entered BB mode
Ping responded in 1 attempt(s)
Inject command 'get-property'
Response status = 0 (0x0) Success.
Response word 1 = 1258488064 (0x4b030100)
Current Version = K3.1.0
```

Figure 4. Running ISP command using CAN interface

5 Revision history

Table 5. Revision history

Document ID	Release date	Description
AN14649 v.1.1	10 December 2025	• Initial public release
AN14649 v.1.0	11 April 2025	• Initial NDA release

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