

Arithmetic Waveform Synthesis with the HC05/08 MCUs

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INTRODUCTION

IThis application note is intended to demonstrate the use of Arithmetic Synthesis to create sinusoidal waveforms from a microcontroller unit (MCU). Given an accumulation constant predefined in memory, a very precise sinusoidal waveform can be produced from a table of sinusoidal values in memory. The values selected from the table are then sent out an MCU port to a digital-to-analog converter (DAC). This application note has been written for the HC08 MCU. Although cycle execution time will be different, the program listing for the HC08 is also applicable to the HC05.

BACKGROUND

The process of producing tones using an accumulated value that is used to point to the next output time (magnitude) sample is called "Arithmetic Synthesis". This is contrasted to Direct Digital Synthesis where the "distance" between each sample taken from sinewave table is constant.

Arithmetic Synthesis utilizes a standard DAC look-up, phase value table consisting of (in this case) 256 phase values for a single cycle of a sine wave. The position in this table is determined by two bytes of data: the MSB which is the integer index into the DAC look-up table, and the LSB which is the fractional depth into the table. Since this fractional portion is not used to directly address a sine sample directly, the effect is evident only when the continual accumulation of this fraction causes an overflow into the integer portion. This effect may be seen in a simple example of repeatedly adding (accumulating) a fixed value while only attributing significance to the integer portion:

Accumulation	Addend	Result		
(Truncated Integer)	(Integer Fraction)	(Integer Fraction)		
0 +	1.25	1.25		
1 +	1.25	2.50		
2 +	1.25	3.75		
3 +	1.25	5.00		
5 +	1.25	6.25		
6 etc				

The effect of the fractional accumulation on the integer portion is an occasionally "skipped" value (like the value of 4 that was skipped above). The integer part of the accumulator is then used to point into the sine table to obtain a magnitude for that time sample. The frequency of occurance of this skipping is a function of the fractional value. Hence, we can determine, with the appropriate choice of fraction and integer, the output

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frequency of the digitized sinewave to a high degree of accuracy. The exact mathematical relationship, for a 256 phase value table, is:

Accumulation Constant = 256 x Desired Frequency x Sampling Period

The sampling period would be:

Sampling Period = E clock period * # of cycles in loop

Once the accumulation constant, D, is determined, it must be put into the memory locations Int_K and Frac_K. This calculation is shown below:

D = 6.575 Int_K = 6 = \$06 Frac_K = 0.575 * 256 = 147.2 = \$93

Once the accumulation constant is defined, the synthesizer is ready to be used. This application note uses the HC08 MCU but the algorithm can be used with any MCU so long as the algorithm is followed and the accumulation constant is defined for the appropriate sampling period.

Arithmetic synthesis produces some artifacts that are not desirable in some applications. One of those artifacts is called "phase noise" (or phase jitter). With an ideal sinewave, the period is fixed and unvarying for every cycle. This means that the instantaneous frequency and the average frequency are the same. What occurs with an arithmetically synthesized waveform, however, is that the instantaneous frequency changes from cycle-to-cycle due to the "sample skipping" performed in the AS algorithm while the average frequency remains quite stable and precise. This cycle-to-cycle variation in instantaneous frequency is called phase noise. Applications which are sensitive to changing instantaneous frequency and/or to the additional spectral components produced by the jitter (these components would be categorized anywhere from distortion to just plain noise, depending on the system) may not want to use AS as the primary method of signal synthesis.

TESTING OF THE ARITHMETIC SYNTHESIZER

In order to test the arithmetic synthesizer, any 8 bit parallel DAC can be used. An Analog Devices AD557JN was used to test our code. The 557 is an easy to use DAC. A basic schematic for the 557 is listed below in Figure #1. The 8 bit digital waveform data is sent to the DAC and the conversion occurs immediately after receiving the information. The sampling period of the waveform is determined by the speed at which data is written to the DAC port. If other MCUs are to be used with this basic circuit, make sure the sampling frequency does exceed the specifed output settling time. Please refer to the AD557 data sheet if more information is needed.







DESCRIPTION OF THE ARITHMETIC SYNTHESIS SOFTWARE

The flowchart and code listing written to illustrate arithmetic synthesis is given at the end of this application note. The file name is called ARSYN8.ASM. The code written to execute the loop routine takes 29 cycles. Assuming the HC08 is running at a speed of 8 MHz, the sampling period would be:

Sampling period = E clock period * 29 cycles = 125nsec * 29 cycles = 3.625 usec

Let's say that you want to produce a sinewave with a frequency of 8 kHz. The accumulation constant will be:

D = 256 * 8000Hz * 3.625usec = 7.424

The accumulation constant must now be put into the memory locations Int_K and Frac_K. These numbers are shown below:



The routine is written using an infinite loop. This is not the most practical application of the algorithm but it allows experimentation and measurement of the waveform. Some applications may need a waveform to last for a specified length of time. This can be done by adding a counter into the loop. The sampling period will be affected so the accumulation constant must be changed to reflect the new sampling period.

The sampling period will change when you use an HC05 MCU. Be sure to recalculate the sampling period with the HC05's bus frequency and cycle counts. The code listed will assemble with an HC05 assembler.

ARSYN8.ASM and can be downloaded from the Freescale MCU Bulletin Board Service. The BBS number is (512) 891-3733. The serial protocol is 1200 or 2400, 8 bits, 1 stop bit, and no parity. The file is located on the CSIC bulletin board in the APPNOTES directory.



ARSYN8 - ARITHMETIC SYNTHESIS FLOWCHART





ARSYN8.ASM - ARITHMETIC SYNTHESIS CODE LISTING

* *	* * * * * * * * * * * * *	* * * * * * * * *	* * * * * * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *		
*						
*	Program Name: ARSYN8.ASM (Arithmetic Synthesizer)					
*	Revision: 1.	00				
*	Date: Februa	ry 3,1993.				
*						
*	Written By:	Mark Glen	ewinkel			
*		CSIC App	lications			
*		1				
Ŷ	Assembled Un	der: P&E	Microcomputer Sy	/stems lasmu8		
*	*****	******	* * * * * * * * * * * * * * * *	* * *		
*	*	Povicio	n Higtory	*		
*	* * * * * *	********	**************************************	* * *		
*						
*	Rev	0 50	12/15/93	M A McOuilken		
*	100 1	0.00	HC05 version to	be translated to HCO8 code		
*						
*	Rev	0.60	01/21/93	M.R. Glenewinkel		
*			Added more comm	nents		
*						
*	Rev	1.00	02/18/93	M.R. Glenewinkel		
*			HC08 version			
*						
* 7	* * * * * * * * * * * * *	* * * * * * * * *	* * * * * * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *		
*						
*	Program Desc	ription:				
*	-1 '		, , ,			
*	This r	This routine produces a sinusoid of a specified frequency at				
*	the ou	the output of a Digital-to-Analog Converter (DAC) attached				
*	LO POL	L A (Sel	by the user) of	all heus.		
*	Basica	llv. this	method utilizes	s a standard DAC look-up table		
*	consis	consisting of (in this case) 256 phase values for a single				
*	cvcle	cycle of a sinewaye. The position in this table is determined				
*	by two	by two bytes of data: the MSB which is the integer index into				
*	the DAC look-up table, and the LSB which is the fractional					
*	depth	into the	table. Since thi	is fractional portion is not		
*	used to directly address a sine sample directly, its effect					
*	is made only when the continual accumulation of this fraction					
*	causes an overflow into the integer portion.					
*		_				
*	We can	determin	e, with the appr	copriate choice of fraction		
*	and in	and integer, the output frequency of the digitized sinewave				
*	to a h	ligh degre	e of accuracy. 'I	l'he exact mathematical		
Ŷ	relati	onsnip, i	or 256 phase val	lues, 1s:		
*	Accumu	lation Co	natant - 256 v r	Desired Frequency y Comple Time		
*	Accullu		1150anii - 200 X L	Septred Frequency & Sample IIme		
*	The ea	mple time	. in this case	is 3.625 used using an HCO8		
*	runnin	g with an	, in chirs case, 8MHz E clock T	The sample period is calculated		
*	bv det	ermining	the number of in	nstructions within the		
*	qenera	ting loop	(29 cyc) and mu	ultiplying the number by the		
*	bus cl	bus clock period. In this example an 8kHz sinewave is to be				
*	sythes	ized. The	accumulation co	onstant will be:		



*		D = 7.424					
* * * * *	Thus, in the source code, the memory locations Int_K and Frac_K should contain \$07 and \$6C, respectively, upon entering the ArithSyn routine.						
· * * * * * * * * * * * * * * * * * * *	**************************************	********** CAUTION ***** impact that code and/or synthesized output frequ at you understand the ra ************************************	<pre>************************************</pre>				
* * * * *	This code assumes tha this case, the testber you've made PortB an **********	t you've got an appropri d consisted of an AD557J output port in your init *******	ate DAC on PortB (in N on PortB) and that ialization code. *********				
*	TASK DATA: Input Variables	Output Variables	Description				
* * * * * * *	Frac_K Int_K		Enter with the appropriate fractional accumulate value. Enter with appropriate integer accumulation				
* * *			value.				
* * * * * * *	LOCAL DATA: Input Variables	Output Variables	value. Description				
* * * * * * * * * * *	LOCAL DATA: Input Variables Cntr	Output Variables Cntr	<pre>value. Description Determines length of time the sinewave is generated with a maximum value of approx 4 5 msec</pre>				
* * * * * * * * * * * * * *	LOCAL DATA: Input Variables Cntr AccumLSB	Output Variables Cntr AccumLSB	Description Determines length of time the sinewave is generated with a maximum value of approx. 4.5 msec. Least significant byte of 16-bit phase accumulator.				
* * * * * * * * * * * * * * * * * * * *	LOCAL DATA: Input Variables Cntr AccumLSB AccumMSB	Output Variables Cntr AccumLSB AccumMSB	<pre>Description Determines length of time the sinewave is generated with a maximum value of approx. 4.5 msec. Least significant byte of 16-bit phase accumulator. Most significant byte of 16-bit phase accumulator. This is the value that is used to point into the sine table.</pre>				
* * * * * * * * * * * * * * * * * * * *	LOCAL DATA: Input Variables Cntr AccumLSB AccumMSB	Output Variables Cntr AccumLSB AccumMSB	<pre>Description Determines length of time the sinewave is generated with a maximum value of approx. 4.5 msec. Least significant byte of 16-bit phase accumulator. Most significant byte of 16-bit phase accumulator. This is the value that is used to point into the sine table. Misc. computational use.</pre>				
* * * * * * * * * * * * * * * * * * * *	LOCAL DATA: Input Variables Cntr AccumLSB AccumMSB ACCA X	Output Variables Cntr AccumLSB AccumMSB ACCA	<pre>Description Determines length of time the sinewave is generated with a maximum value of approx. 4.5 msec. Least significant byte of 16-bit phase accumulator. Most significant byte of 16-bit phase accumulator. This is the value that is used to point into the sine table. Misc. computational use.</pre>				
* * * * * * * * * * * * * * * * * * * *	LOCAL DATA: Input Variables Cntr AccumLSB AccumMSB ACCA X	Output Variables Cntr AccumLSB AccumMSB ACCA X	<pre>value. Description Determines length of time the sinewave is generated with a maximum value of approx. 4.5 msec. Least significant byte of 16-bit phase accumulator. Most significant byte of 16-bit phase accumulator. This is the value that is used to point into the sine table. Misc. computational use. Misc. computational use.</pre>				



PortB DAC *	equ equ	\$01 PortB	
* * * * * * * * * * * * * * * *	* * * * * * * * *	* * * * * * * * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *
* * Memory *			
AccumLSB AccumMSB Frac_K Int_K *	ORG RMB RMB RMB RMB	\$50 1 1 1 1 1	****
START	ORG EQU	\$6E00 *	;beginning of program area
* * * * * * * * * * * * * * * *	* * * * * * * *	* * * * * * * * * * * * * * * * * *	* * * * * * * * * * * * * * * * * * * *
* Main Routine			
* We must prepa * alter our pro	are the vocess.	workspace, any 1	nonzero variables could
ArithSyn	clr clr	AccumLSB AccumMSB	
* At this point * generating th * fraction and * So, basically	we're n ne sinewa an 8-bit 7, we're	ready to actual ave. The accumu t integer. going to have t	ly begin the process of lation is done with an 8-bit the HCO8 do a 16-bit addition:
SignalGen	lda	AccumLSB	;3 - Get current LSB value
	add	Frac_K	; of the phase accum. ;3 - The fractional ; constant is added to ; the LSB of the phase
	sta	AccumLSB	<pre>; accumulator. ;3 - Make sure that ; the updated value is ; kept for the next time ; through the loop.</pre>
* Here's the se* propagate any* AccumLSB and	econd ha v overflo Frac_K	lf of our 16-bit ow from the 8-bi into AccumMSB:	t addition. This will it addition of the
	lda	AccumMSB	;3 - Get current MSB value
	adc	Int_K	 if the phase accum. if added to the MSB of the phase accum. Notice the addition
	sta	AccumMSB	, with carry. ;3 - Save for next time

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* If we've made it here, then we are ready to turn our phase * value into a sine wave at the output of the DAC:

	tax lda sta	SineTable,X DAC	<pre>;1 - ACCA contains the ; integer portion of the ; 16-bit phase value. ; We need to move it into ; the X-reg to do a table ; look-up. ;4 - Get the sine value ;3 - Send it to the DAC ; to create a real-world ; signal.</pre>
	bra	SignalGen	;5 - Branch to top of ; signal generation ; for an infinite loop
* * * * * * * * * * * * * * * *	* * * * * * * *	* * * * * * * * * * * * * * * * * * *	*********
* Tables			
	FCB FCB FCB FCB FCB FCB FCB FCB FCB FCB	<pre>\$99,\$9C,\$9F,\$A2, \$AE,\$B1,\$B3,\$B6, \$C4,\$C7,\$C9,\$CC, \$D5,\$D8,\$DA,\$DC, \$E6,\$E8,\$EA,\$EB, \$F1,\$F3,\$F4,\$F5, \$FA,\$FB,\$FC,\$FD, \$FE,\$FF,\$FF,\$FF, \$FE,\$FF,\$FF,\$FF, \$FE,\$FE,\$FF,\$FF, \$F1,\$F0,\$EF,\$ED, \$E6,\$E4,\$E2,\$E0, \$D5,\$D3,\$D1,\$CE, \$C4,\$C1,\$BF,\$ED, \$E6,\$E4,\$E2,\$E0, \$D5,\$D3,\$D1,\$CE, \$C4,\$C1,\$BF,\$BC, \$AE,\$AB,\$A8,\$A5, \$99,\$96,\$93,\$90, \$80,\$7D,\$7A,\$77, \$6A,\$67,\$64,\$61, \$52,\$4F,\$4D,\$4A, \$3F,\$3C,\$39,\$37, \$2B,\$28,\$26,\$24, \$1C,\$1A,\$18,\$16, \$0F,\$0D,\$0C,\$0B, \$06,\$06,\$05,\$04, \$02,\$01,\$01,\$01, \$01,\$02,\$02,\$02, \$06,\$06,\$07,\$08, \$0D,\$0F,\$10,\$11, \$1A,\$1C,\$1E,\$20, \$28,\$2B,\$2D,\$2F,</pre>	\$A5, \$A8, \$AB \$B9, \$BC, \$BF, \$C1 \$CE, \$D1, \$D3 \$DE, \$E0, \$E2, \$E4 \$ED, \$EF, \$F0 \$F6, \$F8, \$F9, \$FA \$FD, \$FE, \$FF \$FD, \$FC, \$FB \$F6, \$F5, \$F4, \$F3 \$EB, \$EA, \$E8 \$DC, \$DA, \$D8 \$CC, \$C9, \$C7 \$B9, \$B6, \$B3, \$B1 \$A2, \$9F, \$9C \$8C, \$89, \$86, \$83 \$74, \$70, \$6D \$5E, \$5B, \$58, \$55 \$47, \$44, \$41 \$34, \$32, \$2F, \$2D \$22, \$20, \$1E \$15, \$13, \$11, \$10 \$0A, \$08, \$07 \$03, \$03, \$02, \$02 \$01, \$01, \$01 \$03, \$03, \$04, \$05 \$0A, \$0B, \$0C \$13, \$15, \$16, \$18 \$22, \$24, \$26 \$32, \$34, \$37, \$39
	FCB FCB FCB	\$4F,\$52,\$55,\$58, \$67,\$6A,\$6D,\$70,	\$47,\$4A,\$4D \$5B,\$5E,\$61,\$64 \$74,\$77,\$7A,\$7D



* Vector Setup

ORG DW	\$FFFE START	;set	up	reset	vector	
2	011111		αĿ	20000	100002	

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